Singular Perturbations of Stochastic Control Problems with Unbounded Fast Variables

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Plan

- The Two-scale system
- The Optimal Control Problem
- The HJB equation
- The PDE approach to the singular limit $\epsilon \rightarrow 0$
- The effective Hamiltonian H
- The Ergodic Problem (EP)
- Convergence Result
 - Tools
 - Approximation of (EP) by truncation or state constraints
 - Sketch of the proof

Two-scale systems

 $(\Omega, \mathcal{F}, \mathcal{F}_t, \mathbb{P})$ complete filtered probability space.

We consider stochastic control systems with small parameter $\epsilon > 0$ of the form:

$$\begin{cases} dX_s = F(X_s, Y_s, u_s)ds + \sqrt{2}\sigma(X_s, Y_s, u_s)dW_s, & X_{s_0} = x \in \mathbb{R}^n \\ dY_s = -\frac{1}{\epsilon}\xi_s ds + \sqrt{\frac{1}{\epsilon}}\tau(Y_s)d\hat{W}_s, & Y_{s_0} = y \in \mathbb{R}^m. \end{cases}$$

Basic assumptions

• *F* and σ Lipschitz functions in (x, y) uniformly w.r.t. *u*,

$$|F(x, y, u)| + ||\sigma(x, y, u)|| \le C(1 + |x|)$$

+ conditions (later)

•
$$\tau \tau^T = \mathbf{1}$$

• $u \in U$ (compact), ξ takes values in \mathbb{R}^m

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The Optimal Control Problem

For $\theta^* > 1$, we consider Payoff Functionals for $t \in [0, T]$ of the form

$$J^{\epsilon}(t,x,y,\boldsymbol{u},\xi) = \mathbb{E}^{x,y} [\int_{t}^{T} (I(X_{s},Y_{s},\boldsymbol{u}_{s}) + \frac{1}{\theta^{*}} |\xi_{s}|^{\theta^{*}}) ds + g(X_{T})].$$

 $\alpha > 1$

- g continuous, $g(x) \leq C(1+|x|^{lpha})$ and g bounded below
- I contiuous and

$$|I_0|y|^{\alpha} - I_0^{-1} \le |I(x, y, u)| \le I_0^{-1}(1 + |y|^{\alpha})$$

+ conditions (later)

Value Function is:

$$V^{\epsilon}(t,x,y) = \inf_{u,\xi} J^{\epsilon}(t,x,y,u,\xi), \quad 0 \le t \le T$$

Admissible control ξ

Definition

For T > 0, we say that ξ is admissible if

$$\mathbb{E}^{\mathbf{y}}\big[\int_0^T |\xi_{\mathbf{s}}|^{\theta^*} d\mathbf{s}\big] < +\infty.$$

It is possible to see that

- $\mathbb{E}^{x}\left[\int_{0}^{T} |X_{s}|^{\alpha} ds\right] < +\infty$ (standard)
- $\mathbb{E}^{y}\left[\int_{0}^{T} |Y_{s}|^{\alpha} ds\right] < +\infty$ (less standard, uses the admissibility of ξ and $\alpha \leq \theta^{*}$)
- V^{ϵ} is bounded by below
- $|V^{\epsilon}(t, x, y)| \leq C(1 + |x|^{\alpha} + |y|^{\alpha})$ (equi boundedness)

The HJB equation

The HJB equation associated via Dynamic Programming to the value function V^{ϵ} is

$$-V_t^{\epsilon} + H(x, y, D_x V^{\epsilon}, D_{xx}^2 V^{\epsilon}, \frac{D_{xy}^2 V^{\epsilon}}{\sqrt{\epsilon}}) - \frac{1}{2\epsilon} \Delta_y V^{\epsilon} + \frac{1}{\theta} |\frac{D_y V^{\epsilon}}{\epsilon}|^{\theta} = 0$$

with

$$H(x, y, p, M, Z) := \sup_{u} \{-\operatorname{trace}(\sigma \sigma^{T} M) - F \cdot p - \sqrt{2} \operatorname{trace}(\sigma \tau^{T} Z^{T}) - I\}$$

in $(0, T) \times \mathbb{R}^n \times \mathbb{R}^m$ complemented with the terminal condition

$$V^{\epsilon}(T, x, y) = g(x, y)$$

This is a fully nonlinear degenerate parabolic equation.

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Theorem

Suppose $\theta \leq \alpha^*$ where α^* is the conjugate number of α , that is, $\alpha^* = \frac{\alpha}{\alpha-1}$. For any $\epsilon > 0$, the function V^{ϵ} is the unique continuous viscosity solution to the Cauchy problem with at most α -growth in x and y. Moreover the functions V^{ϵ} are locally equibounded.

Uses Comparison principle between sub and super solution to parabolic problems super linear growth conditions (see [Da Lio - Ley 2011]),

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PDE approach to the singular limit $\epsilon \rightarrow 0$

Search *effective Hamiltonian* \overline{H} s. t.

$$V^{arepsilon}(t,x,y)
ightarrow V(t,x) \quad ext{ as } \quad arepsilon
ightarrow 0,$$

V solution of

$$(\overline{\mathsf{CP}}) \qquad \begin{cases} -\frac{\partial V}{\partial t} + \overline{H}\left(x, D_x V, D_{xx}^2 V\right) = 0 & \text{in } (0, T) \times \mathbf{R}^n, \\ V(T, x) = g(x) & \text{in } \mathbf{R}^n \end{cases}$$

The effective Hamiltonian \overline{H}

Finding the candidate limit Cauchy problem of the singularly perturbed problem as $\epsilon \rightarrow 0...$

Ansatz:
$$V^{\epsilon}(t, x, y) = V(t, x) + \epsilon \chi(y)$$
, with $\chi(y) \in C^{2}(\mathbb{R}^{m})$.

We get

$$-V_t + H(x, y, D_x V, D_{xx}^2 V, 0) - \frac{1}{2} \Delta_y \chi + \frac{1}{\theta} |D_y \chi|^{\theta} = 0$$

with $H(x, y, p, M, 0) = \sup_{u} \{-\operatorname{trace}(\sigma \sigma^{T} M) - F \cdot p - I\}.$

We wish that

$$\overline{H}(x, D_x V, D_{xx}^2 V) = H(x, y, D_x V, D_{xx}^2 V, 0) - \frac{1}{2} \Delta_y \chi + \frac{1}{\theta} |D_y \chi|^{\theta}.$$

Idea is to frozen (\bar{t}, \bar{x}) , set $\bar{p} := D_x V(\bar{t}, \bar{x})$ and $\bar{M} := D_{xx}^2 V(\bar{t}, \bar{x})$ and let only *y* varie.

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The effective Hamiltonian \overline{H}

 $\overline{H}(\overline{x},\overline{p},\overline{M})$ is a constant that we will denote by $-\lambda$. Thus

$$\begin{aligned} &-\lambda = H(\bar{x}, y, \bar{p}, \bar{M}, 0) - \frac{1}{2} \Delta_y \chi + \frac{1}{\theta} |D_y \chi|^{\theta} \\ &\Leftrightarrow \lambda - \frac{1}{2} \Delta_y \chi + \frac{1}{\theta} |D_y \chi|^{\theta} = -H(\bar{x}, y, \bar{p}, \bar{M}, 0). \end{aligned}$$

If we call $f(y) := -H(\bar{x}, y, \bar{p}, \bar{M}, 0)$ and impose $\chi(0) = 0$, to avoid the ambiguity of additive constant, we are lead to the following ergodic problem:

$$(EP) \quad \begin{cases} \lambda - \frac{1}{2}\Delta_y \chi + \frac{1}{\theta} |D_y \chi|^{\theta} = f(y) \quad \text{in} \quad \mathbb{R}^m, \\ \chi(0) = 0, \end{cases}$$

where unknown is the pair $(\lambda, \chi) \in \mathbb{R} \times C^2(\mathbb{R}^m)$.

The (EP)

Ergodic Problem

$$\begin{cases} \lambda - \frac{1}{2}\Delta_y \chi + \frac{1}{\theta} |D_y \chi|^{\theta} = f(y) & \text{in } \mathbb{R}^m, \\ \chi(0) = 0. \end{cases}$$

Unknown is the pair $(\lambda, \chi) \in \mathbb{R} \times C^2(\mathbb{R}^m)$.

Such type of ergodic problems were studied by Naoyuki Ichihara in [Ichihara 2012].

Assumptions in [Ichihara 2012]

•
$$f \in C^2(\mathbb{R}^m)$$

• $\exists f_0 > 0 \text{ s.t.}$
 $f_0 |y|^{\alpha} - f_0^{-1} \le f(y) \le f_0^{-1}(1 + |y|^{\alpha})$
(comes from my *I*)

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The (EP) - Results from Ichihara

• (local gradient bounds)

For any r > 0, there exists a constant C > 0 depending only on r, m and θ such that for any solution (λ , χ) of (EP),

$$\sup_{B_r} |D\chi| \leq C(1 + \sup_{B_{r+1}} |f - \lambda|^{\frac{1}{\theta}} + \sup_{B_{r+1}} |Df|^{\frac{1}{2\theta - 1}})$$

•
$$|\chi(\mathbf{y})| \leq C(1+|\mathbf{y}|^{\gamma}) \ (\gamma = \frac{\alpha}{\theta} + 1)$$

(Uniqueness) There exists a unique solution (λ, χ) of (EP) such that χ belongs to

$$\Phi_\gamma:=\{oldsymbol{v}\in C^2(\mathbb{R}^m)\cap C_{oldsymbol{
ho}}(\mathbb{R}^m)|\liminf_{|y| o\infty}rac{
u(y)}{|y|^\gamma}>0\}.$$

H = −λ is the minimum of the constants for which (*EP*) has a solution φ ∈ C²(ℝ^m)

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The (EP)- From Ichihara

Theorem

Let (λ, χ) be a solution of (EP) such that χ is bounded by below. Then,

$$\epsilon\chi(\mathbf{y}) + \lambda(\mathbf{T} - t) = \inf_{\xi \in \mathcal{A}} \mathbb{E}^{\mathbf{y}} \Big[\int_{t}^{T} \big(\frac{1}{\theta^{*}} |\xi_{\mathbf{s}}|^{\theta^{*}} + f(\mathbf{Y}_{\mathbf{s}}^{\xi}) \big) d\mathbf{s} + \epsilon\chi(\mathbf{Y}_{T}^{\xi}) \Big], \quad \mathbf{T} > t.$$

equality is reach for the optimal feedback control ξ^* .

From this result, you can deduce FORMULA (F)

$$egin{aligned} &\epsilon(\chi_1-\chi_2)(y)+(\lambda_1-\lambda_2)(T-t)\leq \mathbb{E}^y[\int_t^Tig(f_1-f_2)(Y^{\xi*}_s)ig)ds]\ &+\epsilon\mathbb{E}^y[(\chi_1-\chi_2)(Y^{\xi*}_T)] \end{aligned}$$

 (λ_i, χ_i) solution of (EP) with χ_i bounded by below and $f = f_i$ (i = 1, 2). ξ^* optimal feedback for (EP) with $f = f_2$.

The Convergence Theorem

Theorem

 $\lim_{\epsilon \to 0} V^{\epsilon}(t, x, y) = V(t, x)$ locally uniformly, V being the unique solution of

$$\begin{cases} -\frac{\partial V}{\partial t} + \overline{H} \left(x, D_x V, D_{xx}^2 V \right) = 0 & \text{in } (0, T) \times \mathbf{R}^n \\ V(T, x) = g(x) & \text{in } \mathbf{R}^n \end{cases}$$

satisfying

$$|V(t,x)| \leq C(1+|x|^{\alpha}).$$

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Tools

• V^{ϵ} equibounded uniformly in ϵ

$$|V^{\epsilon}(t,x,y)| \leq C(1+|x|^{\alpha}+|y|^{\alpha})$$

• $-\infty < u^{\epsilon} \le V^{\epsilon}$ Exists $\rho \in (0, 1)$ s.t $u^{\epsilon}(t, x, y) = (T - t)[\epsilon \rho (1 + |y|^2)^{\frac{\gamma}{2}} - 2f_0^{-1}] + \inf g$ satisfies

$$-\infty < u^{\epsilon} \leq V^{\epsilon}$$

Then the relaxed semilimits

$$\underline{V}(t,x) = \liminf_{\epsilon \to 0, (t',x') \to (t,x)} \inf_{y \in \mathbb{R}^m} V^{\epsilon}(t',x',y),$$

$$\bar{V}_{R}(t,x) = \limsup_{\epsilon \to 0, (t',x') \to (t,x)} \sup_{y \in B_{R}(0)} V^{\epsilon}(t',x',y).$$

are finite!

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\underline{V} is a super solution of the limit PDE

Tools

- Perturbed test function method, evolving from Evans (periodic homogenisation) and Alvarez-M.Bardi (singular perturbations with bounded fast variables).
- approximation of (EP) by truncation

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\underline{V} is a super solution of the limit PDE

Tools

- Perturbed test function method, evolving from Evans (periodic homogenisation) and Alvarez-M.Bardi (singular perturbations with bounded fast variables).
- approximation of (EP) by truncation

$$(EP)_R \quad \begin{cases} \lambda_R - \frac{1}{2}\Delta_y \chi_R + \frac{1}{\theta} |D_y \chi_R|^{\theta} = f(y) \wedge (f_0 |y|^{\alpha - \frac{1}{R}} + R) & \text{in } \mathbb{R}^m, \\ \chi_R(0) = 0. \end{cases}$$

By Ichihara results,

• it has a unique pair of solutions $(\lambda_R, \chi_R) \in \mathbb{R} \times C^2(\mathbb{R}^m)$ such that $\chi_R \in \Phi_{\gamma - \frac{1}{R\theta}}$

• $|\chi_R(y)| \leq C(1+|y|^{\gamma-\frac{1}{R\theta}})$

.

$$(EP)_R \quad \begin{cases} \lambda_R - \frac{1}{2}\Delta_y \chi_R + \frac{1}{\theta} |D_y \chi_R|^{\theta} = f(y) \wedge (f_0 |y|^{\alpha - \frac{1}{R}} + R) & \text{in } \mathbb{R}^m, \\ \chi_R(0) = 0. \end{cases}$$

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By Ichihara results,

- it has a unique pair of solutions $(\lambda_R, \chi_R) \in \mathbb{R} \times C^2(\mathbb{R}^m)$ such that $\chi_R \in \Phi_{\gamma \frac{1}{R\theta}}$
- $|\chi_R(y)| \leq C(1+|y|^{\gamma-\frac{1}{R\theta}})$

Theorem

There exists a sequence $R_j \to \infty$ as $j \to \infty$ s.t. the pair of solutions (λ_R, χ_R) of $(EP)_R$ with $\chi_R \in \Phi_{\gamma - \frac{1}{R\theta}}$ converges to the unique solution $(\lambda \chi)$ of (EP) such that $\chi \in \Phi_{\gamma}$

Sketch of the proof

• $\forall 0 < R' < R$

$$\sup_{B_R'} |D\chi_R| \le C$$

C not depending on R

• Classical theory for quasilinear elliptic equations + Schauder's Theory $\implies |\chi_R|_{2+\Gamma, B'_R}$ is bounded by a constant not depending on R > R'.

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• In particular, $\{\chi_R\}_{R>R'}$ is pre-compact. Namely, $\exists R_j \to \infty$ as $j \to \infty$ and $v \in C^2(\mathbb{R}^m)$ s.t.

$$\chi_{\mathcal{R}_j} o \mathbf{v}, \mathcal{D}\chi_{\mathcal{R}_j} o \mathcal{D}\mathbf{v}, \mathcal{D}^2\chi_{\mathcal{R}_j} o \mathcal{D}^2\mathbf{v} \text{ in } \mathcal{C}^2(\mathbb{R}^m) \text{ as } j o \infty$$

- Formula (F) gives
 - $\lambda_{R_j} \leq \lambda$ • $\lambda_{R_i} \leq \lambda_{R_{i+1}}$

IMPLIES there exists a convergence subsequence, $\lambda_{R_i} \rightarrow c \in \mathbb{R}$

Conclusion: (λ_{R_j}, χ_{R_j}) → (c, ν). BUT χ_{R_j} ∈ Φ_{γ-1/Rθ} and χ_{R_j}(0) = 0, so lim χ_{R_j} = ν ∈ Φ_γ and ν(0) = 0. We are in the right class for which there is uniqueness for (*EP*), ν = χ, c = λ.

Perturbed test function method

<u>*V*</u> is a super solution of the limit PDE () in $(0, T) \times \mathbb{R}^n$?

Fix an arbitrary $(\bar{t}, \bar{x}) \in (0, T) \times \mathbb{R}^n$. This means, if ψ is a smooth function such that $\psi(\bar{t}, \bar{x}) = \underline{V}(\bar{t}, \bar{x})$ and $\underline{V} - \psi$ has a strict minimum at (\bar{t}, \bar{x}) then

$$-\psi_t(\overline{t},\overline{x}) + \overline{H}(\overline{x}, D_x\psi(\overline{t},\overline{x}), D_{xx}^2\psi(\overline{t},\overline{x})) \geq 0.$$

WE ARGUE BY CONTRADICTION. Assume that there exists $\eta > \mathbf{0}$ such that

$$-\psi_t(\bar{t},\bar{x})+\bar{H}(\bar{x},D_x\psi(\bar{t},\bar{x}),D_{xx}^2\psi(\bar{t},\bar{x}))<-2\eta<0.$$

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Perturbed test function method

- Perturbed test function: $\psi^{\epsilon}(t, x, y) = \psi(t, x) + \epsilon \chi_{R}(y)$. χ_{R} , with $R = R_{j}$, in the conditions of last Theorem with fsubstituted by $I(y) = \inf_{|x-\bar{x}|, |t-\bar{t}| < \frac{1}{R}} f_{t,x}(y)$ $(f_{t,x}(y) = -H(x, y, D_{x}\psi(t, x), D_{xx}^{2}\psi(t, x), 0))$
- Then ψ^{ϵ} satisfies

$$-\psi_t^{\epsilon} + H(x, y, D_x\psi^{\epsilon}, D_{xx}^2\psi^{\epsilon}, 0) - \frac{1}{2\epsilon}\Delta_y\psi^{\epsilon} + \frac{1}{\theta}\Big|\frac{D_y\psi^{\epsilon}}{\epsilon}\Big|^{\theta} < 0$$

in

$$Q_{R} =]\overline{t} - \frac{1}{R}, \overline{t} + \frac{1}{R} [\times B_{\frac{1}{R}}(\overline{x}) \times \mathbb{R}^{m}.$$

Perturbed test function method

$$V^{\epsilon}(t,x,y) - \psi^{\epsilon}(t,x,y) \geq u^{\epsilon}(t,x,y) - \psi(t,x) - \epsilon C \big(1 + |y|^{\gamma - \frac{1}{\theta R}}\big) > -\infty.$$

Hence it exists

$$\liminf_{\epsilon \to 0, (t', x') \to (t, x)} \inf_{y \in \mathbb{R}^m} (V^{\epsilon} - \psi^{\epsilon})(t', x', y) > -\infty.$$

Since ψ^{ϵ} is bounded by below, we can conclude that

$$\liminf_{\epsilon \to 0, (t', x') \to (t, x)} \inf_{y \in \mathbb{R}^m} (V^{\epsilon} - \psi^{\epsilon})(t', x', y) = (\underline{V} - \psi)(t, x).$$

But (\bar{t}, \bar{x}) is a strict minimum point of $\underline{V} - \psi$ so the above relaxed lower limit is > 0 on ∂Q_R . Hence we can find

 $\zeta > 0$: $V^{\epsilon} - \zeta \ge \psi^{\epsilon}$ on ∂Q_R for ϵ small.

Claim $V^{\epsilon} - \zeta \ge \psi^{\epsilon}$ in Q_R and Contradiction on the black board.

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\overline{V}_R is a sub solution of a perturbed PDE

$$\begin{cases} -\frac{\partial V}{\partial t} + \overline{H}(x, D_x V, D_{xx}^2 V) - \frac{1}{R} = 0 & \text{in } (0, T) \times \mathbb{R}^n \\ V(T, x) = g(x) & \text{in } \mathbb{R}^n \end{cases}$$

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SP of SCP with Unbounded FV

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\overline{V}_R is a sub solution of a perturbed PDE

Tools

- Perturbed test function method
- approximation of (EP) by state constraints

$$egin{aligned} S(y) &= \sup_{|x-ar{x}|, |t-ar{t}| < rac{1}{R}} f_{t,x}(y) \ & ext{ sub quadratic case } (1 < heta \leq 2) \end{aligned}$$

$$\begin{cases} \lambda_R - \frac{1}{2} \Delta_y \chi_R + \frac{1}{\theta} |D_y \chi_R|^{\theta} = S(y) & \text{in} \quad B_R(0), \\ \chi_R \to +\infty \text{ as } y \to \partial B_R(0), \\ \chi_R(0) = 0. \end{cases}$$

• super quadratic ($\theta > 2$)

$$\begin{cases} \lambda_R - \frac{1}{2}\Delta_y \chi_R + \frac{1}{\theta} |D_y \chi_R|^{\theta} = S(y) & \text{in } B_R(0), \\ \lambda_R - \frac{1}{2}\Delta_y \chi_R + \frac{1}{\theta} |D_y \chi_R|^{\theta} \ge S(y) & \text{on } \partial B_R(0), \\ \chi_R(0) = 0. \end{cases}$$

\bar{V}_R is a sub solution of a perturbed PDE

- Comparison Results for such problems (T. Tchamba's Phd thesis [super quadratic case] + [Barles-Da Lio, 2006] [sub quadratic case]
- \overline{H} is the minimum of the constants for which (*EP*) has a solution $\phi \in C^2(\mathbb{R}^m)$

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$\sup_R \overline{V}_R$ is a sub solution of the limit PDE

• \bar{V}_R is a sub solution of

$$\begin{cases} -\frac{\partial V}{\partial t} + \overline{H}(x, D_x V, D_{xx}^2 V) - \frac{1}{R} = 0 & \text{in} \quad (0, T) \times \mathbf{R}^n \\ V(T, x) = g(x) & \text{in} \quad \mathbf{R}^n \end{cases}$$

for all R large enough

• Since the supremum of sub solutions is a sub solution, we see that $\sup_R \overline{V}_R$ is a sub solution of the limit PDE

$$\begin{cases} -\frac{\partial V}{\partial t} + \overline{H}(x, D_x V, D_{xx}^2 V) = 0 & \text{in } (0, T) \times \mathbf{R}^n \\ V(T, x) = g(x) & \text{in } \mathbf{R}^n \end{cases}$$

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$\sup_R \overline{V}_R$ is a sub solution of the limit PDE

• \bar{V}_R is a sub solution of

$$\begin{cases} -\frac{\partial V}{\partial t} + \overline{H}\left(x, D_x V, D_{xx}^2 V\right) - \frac{1}{R} = 0 & \text{in } (0, T) \times \mathbf{R}^n \\ V(T, x) = g(x) & \text{in } \mathbf{R}^n \end{cases}$$

for all *R* large enough

• Since the supremum of sub solutions is a sub solution, we see that $\sup_R \overline{V}_R$ is a sub solution of the limit PDE

$$\begin{cases} -\frac{\partial V}{\partial t} + \overline{H}(x, D_x V, D_{xx}^2 V) = 0 & \text{in } (0, T) \times \mathbf{R}^n \\ V(T, x) = g(x) & \text{in } \mathbf{R}^n \end{cases}$$

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Comparison Principle and Uniform Convergence

Comparison principle

between sub and super solution to parabolic problems satisfying

$$|V(t,x)| \leq K(1+|x|^{\alpha})$$

(see [Da Lio - Ley 2011]), gives

- uniqueness of solution V of \overline{CP} ,
- $\underline{V}(t,x) \ge \sup_R \overline{V}_R(t,x)$, then $\underline{V} = \sup_R \overline{V}_R = V$ and, as $\epsilon \to 0$,

 $V^{\epsilon}(t, x, y)
ightarrow V(t, x)$ locally uniformly.

associate to the limit PDE a "limit control problem";

Iist examples;

 re-obtain and extend Naoyuki Ichihara results using only PDE methods (partially done);

simpler formula "(F)"?

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- associate to the limit PDE a "limit control problem";
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- associate to the limit PDE a "limit control problem";
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- simpler formula "(F)"?

Grazie !

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SP of SCP with Unbounded FV

Rome, November 2014 29 / 30

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"Sadko in the Underwater Kingdom" by Ilya Repin



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