

The Euler Equations

$$a) \quad \partial_t v + \operatorname{div} \left(\overbrace{v \otimes v - \frac{|v|^2}{n} \mathbb{I}}^A \right) + \nabla \left(\overbrace{p + \frac{|v|^2}{n}}^q \right) = 0$$

$$\operatorname{div} v = 0$$

$$\left[\partial_t \frac{|v|^2}{2} + \operatorname{div} \left(v \left(\frac{|v|^2}{2} + p \right) \right) = 0 \right]$$

Constitutive set :

$$\left. \begin{aligned} v \otimes v - A &= \frac{|v|^2}{n} \mathbb{I} \\ \frac{|v|^2}{2} &= e \end{aligned} \right\} \iff \boxed{v \otimes v - A = \frac{2e}{n} \mathbb{I}}$$

Notation

$$\tau = v \otimes v - A \quad \text{"Reynolds stress"}$$

Observation 1 :

$$a) \quad \iff \operatorname{div} U = 0$$

$$U = \left(\begin{array}{c|c} A + q \mathbb{I} & v \\ \hline v & 0 \end{array} \right)$$

If $U(x) = \bar{U} h(x, \xi)$, then $\operatorname{div} U = \bar{U} \xi h'(x, \xi)$

$$\iff \bar{U} \in \Lambda \iff \det \bar{U} = 0.$$

But actually q doesn't enter in constraint,

and for any $v, A \ni q$ it's $\det \left(\begin{array}{c|c} A + q \mathbb{I} & v \\ \hline v & 0 \end{array} \right) = 0.$

Therefore

$$\boxed{K^\Lambda = K^{co}}$$

$$K = \{(v, A) : v \otimes v - A = \frac{2e}{n} \mathbb{I}\}$$

Fact

$$K^\infty = \left\{ (v, A) : v \otimes v - A \leq \frac{2\epsilon}{n} I \right\}$$

Proof : easy part : $\{v \otimes v - A \leq \frac{2\epsilon}{n} I\} \subseteq K^\infty$

converse : Exercise
Hint prove that

$$\text{extr } \left\{ v \otimes v - A \leq \frac{2\epsilon}{n} I \right\}^\infty \subseteq K$$

by contradiction.

Therefore, inside K^∞ the function

$$(v, A) \mapsto e - \frac{|v|^2}{2}$$

measures how far (v, A) is away from K .

Proposition [The perturbation property holds for $\mathcal{U} = \text{int } K^\infty$
(i.e. $v_0 \otimes v_0 - A_0 < \frac{2\epsilon}{n} I$)

Let $Z_0 = (v_0, A_0, \varphi_0) \in \mathcal{U}$. Then there exists

$(v, A, \varphi) \in C_c^\infty(Q)$ st. $Q = \text{unit cylinder in } (x, t)$

① $(v_0 + v) \otimes (v_0 + v) - (A_0 + A) < \frac{2\epsilon}{n} I \quad \forall (x, t)$

② $\partial_t v + \text{div } A + \nabla \varphi = 0 \quad \& \quad \text{div } v = 0 \quad \text{in } \mathbb{R}^n \times \mathbb{R}$

③ $\iint |v|^2 dx dt \geq c \cdot \left(e - \frac{1}{2} |v_0|^2 \right)^2$

Step 1

(3)

Observation: If $z_1 = (v_1, A_1, q)$, $z_2 = (v_2, A_2, q) \in K$

then $z_1 - z_2 \in \Lambda$

ie. the matrix

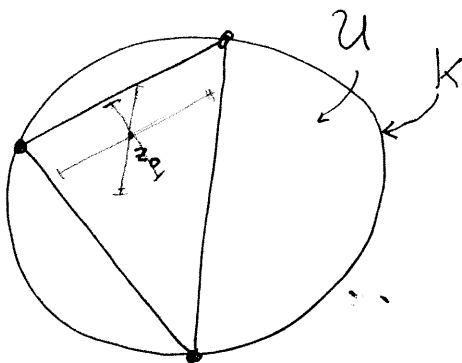
$$\begin{pmatrix} \overbrace{v_1 \otimes v_1 - \frac{|v_1|^2}{n} \mathbb{I}}^{A_1} + q \mathbb{I} & v_1 \\ v_1 & 0 \end{pmatrix} - \begin{pmatrix} \overbrace{v_2 \otimes v_2 - \frac{|v_2|^2}{n} \mathbb{I}}^{A_2} + q \mathbb{I} & v_2 \\ v_2 & 0 \end{pmatrix}$$

has determinant zero. Notice: $|v_1|^2 = |v_2|^2 = 2c$

$$= \begin{pmatrix} v_1 \otimes v_1 - v_2 \otimes v_2 & v_1 - v_2 \\ v_1 - v_2 & 0 \end{pmatrix} \begin{pmatrix} \xi \\ c \end{pmatrix} \quad \begin{matrix} \xi \in \mathbb{R}^n \\ c \in \mathbb{R} \end{matrix}$$

$$= \begin{pmatrix} v_1 \cdot (v_1 \cdot \xi) - v_2 \cdot (v_2 \cdot \xi) + c(v_1 - v_2) \\ v_1 \cdot \xi - v_2 \cdot \xi \end{pmatrix}$$

choose $\xi \perp (v_1 - v_2)$ & $c = -(v_1 \cdot \xi)$



Using Cauchy's inequality,

$$z_0 = \sum_{i=1}^{d+1} \lambda_i z_i \quad z_i \in K$$

Work at constant pressure q .

One of the line segments centered at z_0 in direction $z_i - z_j$, contained in the simplex, has to have length comparable to the distance of z_0 to vertices.

More precisely, assume $\lambda_1 \geq \lambda_2 \geq \dots$

Consider the line segments

$$\left[z_0 - \frac{\lambda_j}{2} (z_j - z_1), z_0 + \frac{\lambda_j}{2} (z_j - z_1) \right]$$

for $j > 1$. These are combined in the simplex, because still have a convex representation.

$$\text{Length} = \lambda_j |z_j - z_1|$$

Choose $j > 1$ with maximum length.

Since
$$z - z_1 = \sum_{j=2}^{d+1} \lambda_j (z_j - z_1)$$

we have
$$|z - z_1| \leq d \max_j |z_j - z_1|$$

so that

$$\lambda_j |z_j - z_1| \geq \frac{1}{d} \text{dist}(z, \text{vertices})$$

Step 2

Construct a compactly supported solution

of
$$\begin{aligned} \Delta v + \text{div } A + \nabla q &= 0 \\ \text{div } v &= 0 \end{aligned}$$

which "behaves" like a plane-wave in direction $z_2 - z_1$ with $z_1, z_2 \in K$.

i.e.
$$\begin{pmatrix} v_1 \otimes v_1 - v_2 \otimes v_2 & v_1 - v_2 \\ v_1 - v_2 & 0 \end{pmatrix}$$

Potentials

ex. 1

$$\text{div } v = 0 \quad \text{in } \mathbb{R}^n$$

find an operator $\mathcal{P}(\nabla)$ s.t. $v = \mathcal{P}(\nabla)\phi$ div free
for any $\phi \in C_c^\infty$ scalar function.

$$\hat{v}(\xi) = \underbrace{\mathcal{P}(\xi)}_{\text{polynomial}} \hat{\phi}(\xi)$$

$$\text{div } \hat{v}(\xi) = \underbrace{\hat{\phi}(\xi) \mathcal{P}(\xi) \cdot \xi}_{\text{vector product}} \quad \text{i.e.} \quad \mathcal{P}(\xi) \perp \xi$$

ex. $\mathcal{P}(\xi) = R\xi$ R antisymmetric R

ex. $R = a \otimes b - b \otimes a$

ex. 2

$$\text{div } U = 0 \quad (n \times n \text{ matrix}), \quad U^T = U; \quad U_{n,n} = 0$$

operator $\mathcal{P}(\nabla)$ with symbol $\mathcal{P}(\xi)$ polynomial

$$\text{s.t.} \quad \mathcal{P}(\xi)\xi = 0; \quad \mathcal{P}^T = \mathcal{P}; \quad \mathcal{P}_{n,n} = 0$$

$$\mathcal{P}(\xi) = R\xi \otimes Q\xi + Q\xi \otimes R\xi$$

for antisymmetric R, Q

$$U_{n,n} = e_n \cdot U e_n = 2(R\xi \cdot e_n)(Q\xi \cdot e_n)$$

pick trace of R $1 \ 0 \ \dots \ 0 = a \otimes b - b \otimes a \quad a \perp b$

ex. 3

$\text{div} U = 0$, $U^T = U$, $U_{n,n} = 0$, $\text{tr} U = 0$

$P(\xi) = R \xi \otimes \xi + Q \xi \otimes \xi$

$\text{tr} P = 2 R \xi \cdot \xi$

$R = a \otimes b - b \otimes a$ with $a, b \perp e_n$

$Q = Q(\xi) = \xi \otimes e_n - e_n \otimes \xi$

then $a, b \perp \text{rg} Q$, so $\text{tr} P = 0$

→ 3rd order polynomial P
 i.e. 3rd order operator
 For Euler do the same in \mathbb{R}^{n+1} time

Fact Given $a, b \in \mathbb{R}^n$ with $|a| = |b|$, $a \neq \pm b$

$\exists \xi \in \mathbb{R}^{n+1} \setminus \{0\}$ s.t.

$$P(\xi) = \begin{pmatrix} a \otimes a - b \otimes b & a - b \\ a - b & 0 \end{pmatrix}$$

Then, if $\phi(y) = \psi(y \cdot \eta)$ $y = (x, t)$

then $P(\nabla) \phi = P(\eta) \psi''$

so plane-waves recovered by the potential P.

Moreover, $\eta \notin e_{n+1}$ (i.e. oscillation not only in time)

Finally, for the proof of the Proposition,

$$\text{take } (v, A, q) \sim \frac{1}{\lambda^3} \rho(\nabla_{(x,t)}) \left\{ \phi(x,t) \sin(\lambda g \cdot (x,t)) \right\}$$

$$= \phi(x,t) \rho(\nabla_{(x,t)}) \sin(\lambda g \cdot (x,t)) + O\left(\frac{1}{\lambda}\right)$$

In particular, upto the cutoff and $O\left(\frac{1}{\lambda}\right)$,

$$v(x,t) \approx \bar{v} \cos(\lambda g \cdot (x,t))$$

$$\text{where } |\bar{v}| \sim \left(e - \frac{1}{2} |y|^2\right)$$



Next, fix

$$X_0 = \left\{ (v, A, q) \in C_c^\infty(\Omega \times]0, \tau[) : \begin{array}{l} \partial_t v + \text{div } A + \nabla q = 0 \quad \downarrow \mathbb{R}^n \times \mathbb{R} \\ \text{div } v = 0 \end{array} \right.$$

$$\text{and } v \otimes v - A < \frac{2}{\epsilon} I \quad \forall (x,t) \in \Omega \times]0, \tau[$$

$\epsilon = 1$

with L^∞ norm : induces a metric on bounded sets

$$\mathbb{I}(v, A, q) = \iint_{\Omega \times]0, \tau[} \left(1 - \frac{|v|^2}{2}\right) dx dt$$

Lemma 3 \implies Proof of Theorem B

$$\text{with } v \in L^\infty(\mathbb{R}^n \times \mathbb{R}), \quad \int_{\Omega \times]0, \tau[} \frac{|v|^2}{2} = 1$$

Lemma: Let $v \in L^\infty([0, T]; L^2(\mathbb{R}^n))$, $A, q \in L^1_{loc}([0, T] \times \mathbb{R}^n)$

be a solution of

$$\partial_t v + \operatorname{div}(A + qI) = 0$$

Then, after redefining v on a set of t 's of measure zero

$$v \in C([0, T]; L^2_w(\mathbb{R}^n)),$$

ie. $t \mapsto \int_{\mathbb{R}^n} v(x, t) \varphi(x) dx$ continuous for any $\varphi \in L^2$.

Proof: For any $\phi \in L^2(\mathbb{R}^n)$, let

$$\Phi(t) = \int_{\mathbb{R}^n} v(x, t) \phi(x) dx$$

Equation $\Rightarrow \Phi \in W^{1,1}$

$\Rightarrow \Phi$ continuous after redefining on a set of measure zero.

RRT \Rightarrow can accordingly redefine $v(x, t)$.

Do this for a countable set $\{\phi_i\}$ which is dense in $L^2(\mathbb{R}^n)$

so that the $\Phi_i(t)$ are v_i . Then for any $\varphi \in L^2$,

an approximate from $\{\phi_i\}$. □

Admissible weak solutions: (v, p)

- $v \in C([0, T]; L^2_w(\mathbb{R}^n))$; $p \in \mathcal{D}'(\mathbb{R}^n \times \mathbb{R})$

- equations satisfied in \mathcal{D}'

- $E(t) = \int_{\mathbb{R}^n} \frac{1}{2} |v|^2 dx$ non-increasing

- $v(0) = v_n$

FACT (P.L.Lions)

Weak - strong uniqueness

If $\exists v \in C^1([0, T] \times \mathbb{R}^n)$ classical solution to IVP,
then v is the unique admissible weak solution.

It is sufficient that $\nabla v + \nabla v^T \in L^1([0, T]; L^\infty(\mathbb{R}^n))$

Theorem B1 (C. De Lellis - Serre)

Let $\Omega \subset \mathbb{R}^n$ open, $\bar{e} \in C(\bar{\Omega} \times]0, T[) \cap C(\partial\Omega];$

and let $(v_0, A_0, q_0) \in C^\infty(\mathbb{R}^n \times]0, T[)$ s.t.

(*)
$$\begin{cases} \partial_t v_0 + \operatorname{div}(A_0 + q_0 I) = 0 & \text{in } \mathbb{R}^n \times]0, T[\\ \operatorname{div} v_0 = 0 \end{cases}$$

(*)
$$v_0 \in C([0, T]; L^2_w(\mathbb{R}^n))$$

(**i)
$$\operatorname{supp}(v_0(t), A_0(t)) \subset\subset \Omega \quad \forall t \in]0, T[$$

(**ii)
$$v_0 \otimes v_0 - A_0 < \frac{2\bar{e}}{n} I \quad \forall (x, t) \in \Omega \times]0, T[$$

Then $\exists (v, p)$ weak solutions of Euler in $\mathbb{R}^n \times]0, T[$

s.t.
$$v \in C([0, T]; L^2_w(\mathbb{R}^n))$$

$$\frac{1}{2} |v(x, t)|^2 = \bar{e} \mathbb{1}_\Omega \quad \forall t \in]0, T[, \text{ a.e. } x \in \mathbb{R}^n$$

$$v(0) = v_0(0) \quad v(T) = v_0(T)$$

$$0 = \operatorname{div} v - \partial_t |v|^2 = 0 - 2\bar{e}$$

The definition of X_0 and I :

$$X_0 = \left\{ v \in C^\infty(\mathbb{R}^n \times]0, T[) \cap C([0, T]; L^2_w(\mathbb{R}^n)) \right.$$

s.t. $\exists A_{\pm} \in C^\infty(\mathbb{R}^n \times]0, T[)$ so that

(i), (ii), (iii), (iv) holds,

$$\left. \begin{aligned} & v(0) = v_0(0), \quad v(T) = v_0(T) \end{aligned} \right\}$$

with the topology of $C([0, T]; L^2_w(\mathbb{R}^n))$

Observe : Since $\bar{e} \in C([0, T]; L^1(\Omega))$ and (iv) holds,

actually $X_0 \subset C([0, T]; Y)$

where Y is a bounded subset of L^2 with weak topology

WLOG Y compact metric space

$\Rightarrow X_0$ metrizable ; $X = \overline{X_0}$

$$I(v) = \sup_t \int_{\Omega} \bar{e}(x,t) - \frac{1}{2} |v(x,t)|^2 dx$$

$$I_{\varepsilon, \Omega_0}(v) = \sup_{\varepsilon \leq t \leq T-\varepsilon} \int_{\Omega_\varepsilon} \bar{e}(x,t) - \frac{1}{2} |v(x,t)|^2 dx$$

The aim is to use lemma 3 again, i.e. to prove

$$\forall v \in X_0 \quad \text{with} \quad \underline{I}(v) \geq \alpha > 0$$

$$\exists v_k \in X_0 \quad \text{with} \quad \begin{cases} v_k \rightarrow v \\ \underline{I}(v_k) \leq \underline{I}(v) - \beta \end{cases}$$

Proposition

$$z_0 = (v_0, A_0) \quad \text{with} \quad v_0 \otimes v_0 - A_0 < \frac{2e}{n} \underline{I}$$

Then $\exists (v_k, A_k) \in C_c^\infty(Q)$ s.t. $Q \equiv [0,1]^n \times \Omega$

① $(v_0 + v_k) \otimes (v_0 + v_k) - (A_0 + A_k) < \frac{2e}{n} \underline{I}$ *forall*

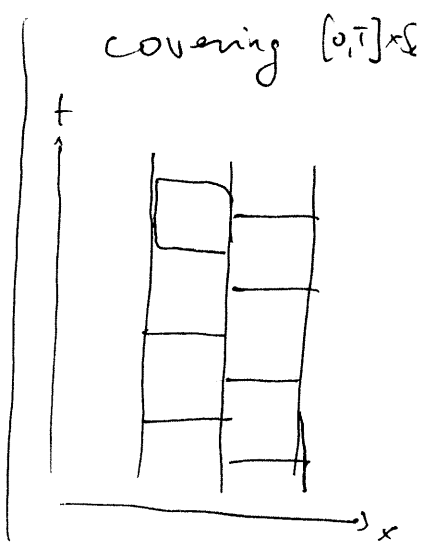
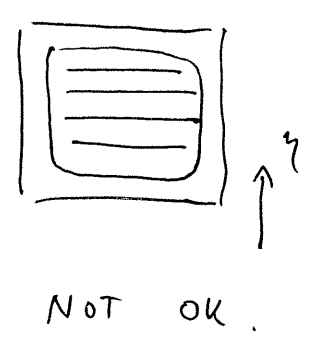
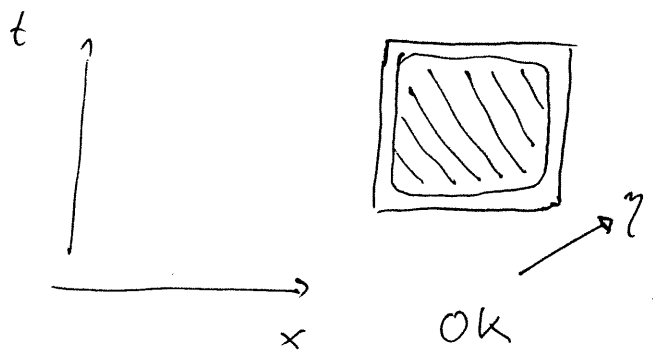
② $\partial_t v_k + \text{div}(A_k + \rho_0 \underline{I}) = 0$; $\text{div} v_k = 0$

③ $\inf_{\frac{1}{4} < t < \frac{3}{4}} \int_{\Omega} |v_k|^2 dx \geq c \cdot (e - \frac{1}{2} |v_0|^2)^2$

④ $v_k \rightarrow 0$ in $C L_w^2$

i.e. $v_k(\cdot, t) \rightarrow 0$ in L^2 uniformly in t .

Main difference to previous:



Beyond L^∞ (or CL_w^2) ?

Recall energy conservation :

$$\partial_t v + \operatorname{div} v \otimes v + \nabla p = 0$$

$$\partial_t v_\varepsilon + \operatorname{div} v_\varepsilon \otimes v_\varepsilon + \nabla p_\varepsilon = \operatorname{div} (v_\varepsilon \otimes v_\varepsilon - (v \otimes v)_\varepsilon)$$

$$\partial_t \frac{|v_\varepsilon|^2}{2} + \operatorname{div} \left(v_\varepsilon \left(\frac{|v_\varepsilon|^2}{2} + p_\varepsilon \right) \right) = \underbrace{v_\varepsilon \cdot \operatorname{div} (v_\varepsilon \otimes v_\varepsilon - (v \otimes v)_\varepsilon)}_{\xrightarrow{\varepsilon \rightarrow 0} 0 \quad ?}$$

Estimates in Hölder spaces (forget time)

Assume $v \in C^\alpha$

Mollify with $\varphi \in C_c^\infty(\mathbb{R}^n)$ symmetric, $\int \varphi = 1$

Then

$$(1) \quad \|v_\varepsilon - v\|_{C^0} \lesssim \varepsilon^\alpha \|v\|_{C^\alpha}$$

~~and more generally~~

~~$$\|v_\varepsilon - v\|_{C^k} \lesssim \varepsilon^{\alpha-k} \|v\|_{C^\alpha}$$~~

$$v * \varphi_\varepsilon - v(x) = \int (v(x-y) - v(x)) \varphi_\varepsilon(y) dy$$

$$(2) \quad \|\nabla v_\varepsilon\|_0 \lesssim \varepsilon^{\alpha-1} \|v\|_\alpha$$

$$v * \nabla \varphi_\varepsilon = \int (v(x-y) - v(x)) \nabla \varphi_\varepsilon(y) dy$$

$$(3) \quad \| (v \cdot w)_\varepsilon - (v_\varepsilon \cdot w_\varepsilon) \|_0 \leq \varepsilon^{2\alpha} \|v\|_\alpha \|w\|_\alpha$$

$$\begin{aligned} (v \cdot w)_\varepsilon - v_\varepsilon \cdot w_\varepsilon &= \int v(x-y) w(x-y) \varphi_\varepsilon(y) dy - v_\varepsilon \cdot w_\varepsilon \\ &= \int (v(x-y) - v(x)) (w(x-y) - w(x)) \varphi_\varepsilon(y) dy \\ &\quad + v \cdot w_\varepsilon + w \cdot v_\varepsilon - v \cdot w - v_\varepsilon \cdot w_\varepsilon \\ &= \int (v(x-y) - v(x)) (w(x-y) - w(x)) \varphi_\varepsilon(y) dy \\ &\quad - (v - v_\varepsilon) \cdot (w - w_\varepsilon) \end{aligned}$$

$$\text{So } \partial_t \int |v_\varepsilon|^2 dx = - \int \underbrace{\nabla v_\varepsilon}_{\varepsilon^{\alpha-1}} \cdot \underbrace{(v_\varepsilon \otimes v_\varepsilon - (v \otimes v)_\varepsilon)}_{\varepsilon^{2\alpha}}$$

so converges to zero if $\alpha > \frac{1}{3}$

Osager

Same exponent for Kolmogorov:

hypothesis: energy cascade (\approx self-similarity)

$$\partial_t v + \text{div}(v \otimes v) + \nabla p = \nu \Delta v$$

on length-scale L , time-scale T ($v \sim \frac{L}{T}$), $|\partial v| \sim |\text{div}(v \otimes v)| \sim \frac{L}{T^2}$

so $\nu \sim \frac{L^2}{T}$. Energy dissipation $= \nu |\nabla v|^2 \sim \frac{L^2}{T^3} = \text{const.} \Rightarrow v \sim L^{\frac{2}{3}}$