

Liquid crystal flows with free boundary

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Nematic liquid crystal flow in dimension two

We consider the following initial-boundary value problem of nematic liquid crystal flow in a bounded, smooth domain Ω in \mathbb{R}^n ($n \geq 2$), and $T > 0$

$$\text{(NLCF)} \quad \begin{cases} \partial_t v + v \cdot \nabla v + \nabla P = \Delta v - \varepsilon_0 \nabla \cdot \left(\nabla u \odot \nabla u - \frac{1}{2} |\nabla u|^2 \mathbb{I}_2 \right) \\ \nabla \cdot v = 0 \\ \partial_t u + v \cdot \nabla u = \Delta u + |\nabla u|^2 u, \end{cases}$$

$$(v, u)|_{t=0} = (v_0, u_0) \quad \text{in } \Omega,$$

$$v = 0 \quad \text{on } \partial\Omega \times (0, T), \quad u = u_0 \quad \text{on } \partial\Omega \times (0, T),$$

- ▶ $v : \Omega \times (0, T) \rightarrow \mathbb{R}^n$ fluid velocity
- ▶ $P : \Omega \times (0, T) \rightarrow \mathbb{R}$ fluid pressure
- ▶ $u : \Omega \times (0, T) \rightarrow \mathbb{S}^2$ orientation field of nematic liquid crystal molecules
- ▶ $\varepsilon_0 > 0$: competition between kinetic energy and elastic energy

Nematic liquid crystal flow

(NLCF) is a simplified version of the Ericksen–Leslie model first proposed by [Lin 1989](#). (NLCF) couples two important PDEs:

- ▶ Incompressible Navier–Stokes equation

$$\text{(iNS)} \quad \begin{cases} \partial_t v + v \cdot \nabla v + \nabla P = \Delta v & \text{in } \Omega \times (0, T) \\ \nabla \cdot v = 0 & \text{in } \Omega \times (0, T) \end{cases}$$

- ▶ Harmonic map heat flow

$$\text{(HMF)} \quad \begin{cases} \partial_t u = \Delta u + |\nabla u|^2 u & \text{in } \Omega \times (0, T) \\ u : \Omega \times (0, T) \rightarrow \mathbb{S}^2 \end{cases}$$

Coupling terms

- ▶ (HMF) provides **forcing term** to (iNS)

$$-\varepsilon_0 \nabla \cdot \left(\nabla u \odot \nabla u - \frac{1}{2} |\nabla u|^2 \mathbb{I}_2 \right)$$

- ▶ (iNS) provides **transport term** to (HMF) $v \cdot \nabla u$

(iNS) and (HMF)

▶ (iNS)

- ▶ Existence of suitable weak solutions: Leray 1934, Hopf 1951
Leray–Hopf solution is regular in \mathbb{R}^2
- ▶ Partial regularity results in \mathbb{R}^3 : Caffarelli–Kohn–Nirenberg 1982, Lin 1998

▶ (HMF)

- ▶ $n = 2$, Struwe (1985) established the existence of global weak solution, which has **at most finitely many** singular points
- ▶ $n \geq 3$: existence of global weak solutions Chen–Struwe 1989, Chen–Lin 1993
- ▶ $n \geq 3$: examples of finite time blow-up Coron–Ghidaglia 1989, Chen–Ding 1990
- ▶ $n = 2$: **critical dimension**. Finite time blow-up
Chang–Ding–Ye 1991
van den Berg–Hulshof–King 2003 (formal analysis)
Raphaël–Schweyer 2013
Dávila–del Pino–Wei 2017 (blow-up at multiple points in general domains)

NLCF

- ▶ Existence of weak solutions and partial regularity results for $n = 2, 3$: [Lin–Liu 1995, 1996](#)
- ▶ $n = 2$: [Lin-Lin-Wang \(2010\)](#) proved the global existence of Leray–Hopf type weak solutions for (NLCF) that is **smooth away from finitely many points**.
- ▶ $n = 2$: [Lin-Wang \(2010\)](#) proved the uniqueness of Leray-Hopf weak solution to (NLCF)
- ▶ $n = 3$: [Lin-Wang \(2016\)](#) proved the global existence of weak solutions satisfying the global energy inequality under the assumption that the initial orientation field $d_0(\Omega) \subset \mathbb{S}_+^2$.
- ▶ Blow-solutions in two dimensions at a finite number of points by [Lai-Lin-Wei-Wang-Zhou \(2021\)](#)

A new model with free boundary (F.H. Lin, Y. S., J. Wei, Y. Zhou)

$$\text{(LCF)} \quad \begin{cases} \partial_t v + v \cdot \nabla v + \nabla P = \Delta v - \varepsilon_0 \nabla \cdot \left(\nabla u \odot \nabla u - \frac{1}{2} |\nabla u|^2 \mathbb{I}_2 \right) \\ \nabla \cdot v = 0 \\ \partial_t u + v \cdot \nabla u = \Delta u + |\nabla u|^2 u, \end{cases}$$

$$\text{(FB)} \quad \begin{cases} v \cdot \nu = 0, & \text{on } \partial\Omega \times (0, T), \\ (Sv \cdot \nu)_\tau = 0, & \text{on } \partial\Omega \times (0, T), \\ u(x, t) \in \Sigma, & \text{on } \partial\Omega \times (0, T), \\ \frac{\partial u}{\partial \nu}(x, t) \perp T_{u(x,t)}\Sigma, & \text{on } \partial\Omega \times (0, T), \end{cases}$$

where ν is the unit outer normal of $\partial\Omega$, S is the strain tensor (deformation tensor, shear stress)

$$Sv = \frac{1}{2}(\nabla v + (\nabla v)^T),$$

The blow-up result via parabolic gluing

We construct both interior and boundary bubbling in the half-plane:

Theorem (F.H. Lin, Y. S., J. Wei, Y. Zhou)

For $T > 0$ sufficiently small and any given points in $\overline{\mathbb{R}_+^2}$, there exists initial data (u_0, v_0) such that the solution (u, v) to liquid crystal flow with free boundary conditions blows up at finite time T exactly at these given points. Moreover, u takes the form at leading order of the sharply scaled 1-corotational profile (equivariant harmonic map) with type II rate

$$\lambda(t) \sim \frac{T - t}{|\log(T - t)|^2}.$$

Inner-outer gluing method for parabolic equations

- ▶ good approximation \implies small error

- ▶ $u = \text{approximation} + \overbrace{\eta_R \phi(y, t)}^{\text{perturbation}} + \underbrace{\psi(x, t)}_{\text{outer}}, \quad y = \frac{x - \xi(t)}{\lambda(t)}$

- ▶ **Inner problem:** $\lambda^2 \phi_t = L[\phi] + \underbrace{\text{coupling}(\psi)}_{\mathcal{H}} + \text{error}$

- ▶ **Outer problem** (maximum principle):

$$\psi_t = \Delta_x \psi + \underbrace{(\phi \Delta \eta_R + 2 \nabla \eta_R \cdot \nabla \phi)}_{\text{coupling}} + \text{nonlinear terms} + \text{error}$$

- ▶ Orthogonality conditions ($\{Z_j\}$ span the kernel around a "bubble")

- ▶ $\int \mathcal{H} Z_j dy = 0 \implies$ good inner solution

- ▶ $\int \mathcal{H} Z_j dy = 0 \implies$ reduced equations for λ, ξ

- ▶ Fixed point argument: ϕ, ψ, λ, ξ

A crucial tool for the study: estimates of Stokes operator with Navier B.C.

Consider the following Stokes system

$$\left\{ \begin{array}{ll} \partial_t v + \nabla P = \Delta v + F, & \text{in } \mathbb{R}_+^2 \times (0, \infty), \\ \nabla \cdot v = 0, & \text{in } \mathbb{R}_+^2 \times (0, \infty), \\ \partial_{x_2} v_1 \Big|_{x_2=0} = 0, \quad v_2 \Big|_{x_2=0} = 0, \\ v \Big|_{t=0} = 0, \end{array} \right. \quad (0.1)$$

F is solenoidal:

$$\nabla \cdot F = 0, \quad F_2 \Big|_{x_2=0} = 0.$$

Theorem (F.H. Lin, Y. S., J. Wei, Y. Zhou)

The solution to (0.1) with solenoidal forcing can be expressed in the form

$$v(x, t) = \int_0^t \int_{\mathbb{R}_+^2} \mathcal{G}^0(x, y, t - \tau) F(y, \tau) dy d\tau + \int_0^t \int_{\mathbb{R}_+^2} \mathcal{G}^*(x, y, t - \tau) \int_0^\tau F(y, s) ds dy d\tau \quad (0.2)$$

$$P(x, t) = \int_0^t \int_{\mathbb{R}_+^2} \mathcal{P}(x, y, t - \tau) \cdot F(y, \tau) dy d\tau$$

$$|\partial_t^s D_x^k D_y^m P_j(x, y, t)| \lesssim t^{-1-s-\frac{m_2}{2}} (|x - y^*|^2 + t)^{-\frac{1+|k|+|m'|}{2}} e^{-\frac{cy_2^2}{t}},$$
$$|\partial_t^s D_x^k D_y^m G_{ij}^*(x, y, t)| \lesssim t^{-1-s-\frac{m_2}{2}} (|x - y^*|^2 + t)^{-\frac{2+|k|+|m'|}{2}} e^{-\frac{cy_2^2}{t}}. \quad (0.3)$$

See Solonnikov for others B.C.

Heat flow of harmonic maps with free boundary

Let (M, g) be an m -dimensional smooth Riemannian manifold with boundary ∂M and N be another smooth compact Riemannian manifold without boundary. Suppose Σ is a k -dimensional submanifold of N without boundary. Any continuous map $u_0 : M \rightarrow N$ satisfying $u_0(\partial M) \subset \Sigma$ defines a relative homotopy class in maps from $(M, \partial M)$ to (N, Σ) . A map $u : M \rightarrow N$ with $u(\partial M) \subset \Sigma$ is called homotopic to u_0 if there exists a continuous homotopy $h : [0, 1] \times M \rightarrow N$ satisfying $h([0, 1] \times \partial M) \subset \Sigma$, $h(0) = u_0$ and $h(1) = u$. An interesting problem is that whether or not each relative homotopy class of maps has a representation by harmonic maps, which is equivalent to the following problem:

$$\begin{cases} -\Delta u = \Gamma(u)(\nabla u, \nabla u), \\ u(\partial M) \subset \Sigma, \\ \frac{\partial u}{\partial \nu} \perp T_u \Sigma. \end{cases} \quad (0.4)$$

Here ν is the unit normal vector of M along the boundary ∂M , $\Delta \equiv \Delta_M$ is the Laplace-Beltrami operator of (M, g) , Γ is the second fundamental form of N (viewed as a submanifold in \mathbb{R}^ℓ via Nash's isometric embedding), $T_p N$ is the tangent space in \mathbb{R}^ℓ of N at p and \perp means orthogonal in \mathbb{R}^ℓ . (0.4) is the Euler-Lagrange equation for critical points of the Dirichlet energy functional

$$E(u) = \int_M |\nabla u|^2 dv_g$$

defined over the space of maps

$$H_\Sigma^1(M, N) = \{u \in H^1(M, N) : u(x) \subset \Sigma \text{ a.e. } x \in \partial M\}.$$

Existence by flow (see [Eells-Sampson](#) for standard harmonic maps)

$$\begin{cases} \partial_t u - \Delta u = \Gamma(u)(\nabla u, \nabla u) & \text{on } M \times [0, \infty), \\ u(x, t) \in \Sigma & \text{on } \partial M \times [0, \infty), \\ \frac{\partial u}{\partial \nu}(x, t) \perp T_{u(x,t)}\Sigma & \text{on } \partial M \times [0, \infty) \\ u(\cdot, 0) = u_0 & \text{on } M. \end{cases} \quad (0.5)$$

Weak solutions of the harmonic map heat flow with FB

Take $M = \mathbb{R}_+^{n+1}$ and $N = \mathbb{R}^\ell$. We will try to solve the following regularized version of the heat flow (**extrinsic version**):

$$\left\{ \begin{array}{ll} \partial_t u - \Delta u = 0 & \text{in } \mathbb{R}_+^{n+1} \times \mathbb{R}_+, \\ u(x, 0, t) \in \Sigma & x \in \mathbb{R}^n, t > 0, \\ - \lim_{y \rightarrow 0^+} \frac{\partial u}{\partial y}(x, y, t) \perp T_{u(x,0,t)} \Sigma & x \in \mathbb{R}^n, t > 0, \\ u(x, y, 0) = u_0(x, y) & (x, y) \in \mathbb{R}_+^{n+1}. \end{array} \right. \quad (0.6)$$

We focus on the study of (0.6) for

$$\Sigma = \mathbb{S}^{\ell-1}$$

Intrinsic version: Hamilton, Struwe, Chen-Lin

Harmonic maps with free boundary and their geometric interest

$$\begin{cases} -\Delta u = \Gamma(u)(\nabla u, \nabla u), \\ u(\partial M) \subset \Sigma, \\ \frac{\partial u}{\partial \nu} \perp T_u \Sigma. \end{cases}$$

- ▶ Existence and regularity: Nitsche, Hildebrandt, Jost, Duzaar-Steffen, Hardt-Lin, etc...
- ▶ New point of view via half-harmonic maps: Da Lio-Rivière, Millot-S., Da Lio-Rivière-Laurain
- ▶ Branched minimal immersions with free boundary and spectral geometry of extremal Steklov eigenvalues: Fraser-Schoen, Karpukhin, Laurain-Petrides, etc..

Ginzburg-Landau approximation

Given $U_0 \in \dot{H}^1(\mathbb{R}_+^{n+1}, \mathbb{S}^{\ell-1})$ and $\varepsilon > 0$, consider

$$\begin{cases} (\partial_t - \Delta)U_\varepsilon(x, y, t) = 0 & \text{in } \mathbb{R}_+^{n+1} \times (0, \infty), \\ U_\varepsilon(x, y, 0) = U_0(x, y) & \text{in } \mathbb{R}_+^{n+1}, \\ \frac{\partial U_\varepsilon}{\partial y} = -\frac{1}{\varepsilon^2}(1 - |U_\varepsilon|^2)U_\varepsilon & \text{on } \partial\mathbb{R}_+^{n+1} \times (0, \infty). \end{cases} \quad (0.7)$$

For fixed $\varepsilon > 0$, (0.7) is the gradient flow of

$$E_\varepsilon(U) = \int_{\mathbb{R}_+^{n+1}} \frac{1}{2} |\nabla U|^2 dx dy + \int_{\partial\mathbb{R}_+^{n+1}} \frac{(1 - |U|^2)^2}{4\varepsilon^2} dx.$$

There exist smooth solutions $U_\varepsilon : \mathbb{R}_+^{n+1} \times (0, \infty) \rightarrow \mathbb{R}^L$ of (0.7):

$$\begin{aligned} & E_\varepsilon(U_\varepsilon)(t) + \int_0^t \int_{\mathbb{R}_+^{n+1}} |\partial_t U_\varepsilon|^2 dx dy dt \\ & \leq E_\varepsilon(U_0) = \int_{\mathbb{R}_+^{n+1}} \frac{1}{2} |\nabla U_0|^2 dx dy. \end{aligned} \quad (0.8)$$

For $U_0 \in H^1(\mathbb{R}_+^{n+1}, \mathbb{S}^{L-1})$, let $u_0 = U_0|_{\partial\mathbb{R}_+^{n+1}}$. Let \mathcal{P}^k denote the k -dimensional Hausdorff measure on $\mathbb{R}^{n+1} \times \mathbb{R}$ with respect to

$$\delta((X, t), (Y, s)) = \max \{ |X - Y|, \sqrt{|t - s|} \}.$$

Theorem (A. Hyder, A. Segatti, Y. S., C. Wang)

1) $\exists U_* \in L^\infty(\mathbb{R}_+, H^1(\mathbb{R}_+^{n+1}, \mathbb{S}^{\ell-1}))$ with $\partial_t U_* \in L^2(\mathbb{R}_+^{n+1} \times \mathbb{R}_+)$ solving

$$\begin{cases} (\partial_t - \Delta)U_* = 0 & \text{in } \mathbb{R}_+^{n+1} \times (0, \infty), \\ U_*|_{t=0} = U_0 & \text{on } \mathbb{R}_+^{n+1}, \\ U_*(x, 0, t) \in N; \quad \frac{\partial U_*}{\partial y}(x, 0, t) \perp T_{U_*(x,0,t)}N & \text{on } \mathbb{R}^n \times (0, \infty). \end{cases}$$

such that $U_\varepsilon \rightharpoonup U_*$ in $H^1(\mathbb{R}_+^{n+1} \times \mathbb{R}_+)$.

2) $\exists \Sigma \subset \partial\mathbb{R}_+^{n+1} \times (0, \infty)$, with $\mathcal{P}^{n+1}(\Sigma) < \infty$, such that

$$U_\varepsilon \rightarrow U_* \in C_{loc}^2(\overline{\mathbb{R}_+^{n+1} \times (0, \infty)} \setminus \Sigma).$$

Theorem (Continued)

3) Set $u_* = U_*|_{\partial\mathbb{R}_+^{n+1} \times [0, \infty)}$. Then $u_* \in C^\infty(\mathbb{R}^n \times (0, \infty) \setminus \Sigma)$ solves the $\frac{1}{2}$ -harmonic map heat flow:

$$\begin{cases} (\partial_t - \Delta)^{\frac{1}{2}} u_* \perp T_{u_*} \mathbb{S}^{L-1} & \text{in } \mathbb{R}^n \times (0, \infty), \\ u_*(x, 0) = u_0(x) & \text{in } \mathbb{R}^n. \end{cases} \quad (0.9)$$

4) For any $C_0 > 0$, $\exists \epsilon_0 > 0$ such that if

$$\|\nabla U_0\|_{L^\infty(\mathbb{R}_+^{n+1})} \leq C_0, \quad E(U_0) \leq \epsilon_0,$$

$U_* \in C^\infty(\overline{\mathbb{R}_+^{n+1}} \times (0, \infty))$ ($\Rightarrow u_* = U_*|_{\partial\mathbb{R}_+^{n+1} \times [0, \infty)} \in C^\infty$).

Why is the LCF with FB model physical ?

We first derive the energy law. Multiply by v and integrate over Ω :

$$\frac{1}{2} \frac{d}{dt} \int_{\Omega} |v|^2 + \int_{\Omega} (v \cdot \nabla v) \cdot v + \int_{\Omega} \nabla P \cdot v = - \int_{\Omega} |\nabla v|^2 - \int_{\Omega} (\Delta u \cdot \nabla u) \cdot v,$$

where we have used

$$\nabla \cdot \left(\nabla u \odot \nabla u - \frac{1}{2} |\nabla u|^2 \mathbb{I}_2 \right) = \Delta u \cdot \nabla u.$$

And

$$\int_{\Omega} (v \cdot \nabla v) \cdot v = \int_{\Omega} \nabla P \cdot v = 0.$$

So we have

$$\frac{1}{2} \frac{d}{dt} \int_{\Omega} |v|^2 = - \int_{\Omega} |\nabla v|^2 - \int_{\Omega} (\Delta u \cdot \nabla u) \cdot v. \quad (0.10)$$

Multiply with $\Delta u + |\nabla u|^2 u$ and integrate over Ω

$$-\frac{1}{2} \frac{d}{dt} \int_{\Omega} |\nabla u|^2 + \int_{\Omega} (v \cdot \nabla u) \cdot (\Delta u + |\nabla u|^2 u) = \int_{\Omega} |\Delta u + |\nabla u|^2 u|^2.$$

Since

$$\int_{\Omega} (v \cdot \nabla u) \cdot (|\nabla u|^2 u) = \int_{\Omega} |\nabla u|^2 v \cdot \frac{\nabla(|u|^2)}{2} = 0,$$

we obtain

$$-\frac{1}{2} \frac{d}{dt} \int_{\Omega} |\nabla u|^2 + \int_{\Omega} (\Delta u \cdot \nabla u) \cdot v = \int_{\Omega} |\Delta u + |\nabla u|^2 u|^2. \quad (0.11)$$

Combining (0.10) and (0.11), we get

$$\frac{1}{2} \frac{d}{dt} \left(\int_{\Omega} |v|^2 + |\nabla u|^2 \right) = - \int_{\Omega} |\nabla v|^2 - \int_{\Omega} |\Delta u + |\nabla u|^2 u|^2 \quad (0.12)$$

which is called *the basic energy law* (energy dissipation).

On the other hand, the physical compatibility condition should be satisfied

$$\left\langle \left(\frac{\nabla v + (\nabla v)^T}{2} - P\mathbb{I}_2 - \nabla u \odot \nabla u \right) \nu, \tau \right\rangle = 0, \quad \text{on } \partial\Omega, \quad (0.13)$$

where

$$\nabla \cdot \left(\frac{\nabla v + (\nabla v)^T}{2} - P\mathbb{I}_2 - \nabla u \odot \nabla u \right)$$

is called *stress tensor*. It is easy to see that $\langle P\mathbb{I}_2 \nu, \tau \rangle = 0$ as $\langle \nu, \tau \rangle = 0$. Also,

$$\left\langle \frac{\nabla v + (\nabla v)^T}{2} \nu, \tau \right\rangle = 0$$

is the *Navier boundary condition* and

$$0 = \langle (\nabla u \odot \nabla u) \nu, \tau \rangle = \langle \nabla_\nu u, \nabla_\tau u \rangle$$

implies the free boundary condition

$$\frac{\partial u}{\partial \nu} \perp T_u \Sigma \quad \text{on } \partial\Omega \times (0, T).$$

Symmetry encoded in the free boundary condition

Since on $\partial\mathbb{R}_+^2$ one has

$$\begin{cases} u(x, t) \in \Sigma, \\ \frac{\partial u}{\partial \nu}(x, t) \perp T_{u(x, t)}\Sigma, \end{cases} \implies \begin{cases} \partial_{x_2} u_1 = 0, \\ \partial_{x_2} u_2 = 0, \\ u_3 = 0, \end{cases} \quad (0.14)$$

and

$$\begin{cases} v \cdot \nu = 0, \\ (Sv \cdot \nu)_\tau = 0, \end{cases} \implies \begin{cases} \partial_{x_2} v_1 = 0, \\ v_2 = 0, \end{cases} \quad (0.15)$$

then even reflection for u_1, u_2, v_1 and odd reflection for u_3, v_2 :

$$\tilde{u}(x_1, x_2, t) = \begin{pmatrix} u_1(x_1, -x_2, t) \\ u_2(x_1, -x_2, t) \\ -u_3(x_1, -x_2, t) \end{pmatrix}, \quad \tilde{v}(x_1, x_2, t) = \begin{pmatrix} v_1(x_1, -x_2, t) \\ -v_2(x_1, -x_2, t) \end{pmatrix}, \quad (0.16)$$

is such that the free boundary conditions are satisfied.

With the previous reflections and

$$\tilde{P}(x_1, x_2, t) = P(x_1, -x_2, t), \quad (0.17)$$

the structure of the equation is preserved, i.e.,

$$\begin{cases} \partial_t \tilde{u} + \tilde{v} \cdot \nabla \tilde{u} = \Delta \tilde{u} + |\nabla \tilde{u}|^2 \tilde{u}, \\ \partial_t \tilde{v} + \tilde{v} \cdot \nabla \tilde{v} + \nabla \tilde{P} = \Delta \tilde{v} - \nabla \cdot \left(\nabla \tilde{u} \odot \nabla \tilde{u} - \frac{1}{2} |\nabla \tilde{u}|^2 \mathbb{I}_2 \right), \\ \nabla \cdot \tilde{v} = 0. \end{cases} \quad (0.18)$$

Open problems

- ▶ Caffarelli-Kohn-Nirenberg partial regularity of suitable solutions in two dimensions
- ▶ Global Weak solutions in three dimensions
- ▶ Coupling surface diffusion with heat flows of harmonic maps (Vorticity formulation with compensated-compactness phenomena with the Hopf differential)
- ▶ (Heat flow of) Harmonic maps with free boundary: Rigidity *à la Siu-Sampson* for manifolds with boundary, singular domains/targets, Teichmüller flow on moduli space of hyperbolic metrics on surfaces with boundary

THANK YOU