Surfaces with conformal second fundamental form

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RIASSUNTO – In questo lavoro si studiano le sottovarietà M di una varietà Riemanniana N con seconda forma quadratica conforme; il problema ha interesse solo in codimensione maggiore di uno ed è collegato alla armonicità dell'applicazione sferica di Gauß. Il risultato principale è una classificazione completa delle superficie compatte di una varietà a curvatura costante semplicemente connessa con curvatura media parallela e con seconda forma quadratica conforme; in particolare viene ottenuta una nuova caratterizzazione del toro di Clifford e della superficie di Veronese.

ABSTRACT – The subject of the present paper is the study of the submanifolds M of a Riemannian manifold N with conformal second fundamental form. The question is interesting only in codimension greater than one and is related to the harmonicity of the spherical Gauß map. The main result is a complete classification of compact surfaces of a space form with parallel mean curvature and with conformal second fundamental form; in particular a new characterization for the Clifford torus and the Veronese surface is given.

KEY WORDS - Spherical Gauß map - Harmonic maps - Submanifolds with conformal second fundamental form - Minimal submanifolds - Submanifolds with parallel mean curvature vector field.

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1 - Introduction

A Riemannian immersion $f: M \to N$ induces a map of the unit

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normal bundle of M in the unit tangent bundle of N, defined by

$$\nu_f: TM_1^{\perp} \to TN_1$$

$$(1.1) \qquad (x, v) \mapsto (f(x), v); \qquad x \in M, \qquad v \in T_x M_1^{\perp}.$$

In other words ν_f sends a unit normal vector to M to itself, considered as a unit vector in N; ν_f is called the spherical Gauß map.

JENSEN and RIGOLI [6] endowed the bundles TM_1^{\perp} and TN_1 with a Sasaki like metric and studied the conditions under which ν_f is harmonic. One of these conditions is that the second fundamental form h of the immersion must be conformal. It can be expressed as follows: let (e_i) $i=1,...,m=\dim M$ be an orthonormal moving frame on M, then h is conformal if, for any field v and w on TM^{\perp}

(1.2)
$$\sum_{i,j=1}^{m} (h(e_i,e_j),v)(h(e_i,e_j),w) = \lambda^2(v,w),$$

where (,) denotes the inner product in N and λ is a suitable scalar function on M.

If M is a hypersurface of N, it is trivially true that h is conformal.

An important result on the harmonicity of the spherical Gauß map is the following ([6], compare also [9]): if N is a space form, $\operatorname{codim}(M) > 1$ and either

- (a) M is minimal in N or
- (b) M has parallel mean curvature in N

then the spherical Gauß map is harmonic or vertically harmonic respectively if and only if f has conformal second fundamental form (vertically harmonic means that the component of the tension field of ν_f tangent to the fibre of the bundle TN_1 vanishes).

The aim of the present paper is to characterize all surfaces M isometrically immersed in a n-dimensional space form $\mathbb{R}^n(c)$ of constant curvature c with conformal second fundamental form for which either (a) or (b) holds and $\operatorname{codim}(M) > 1$.

An easy codimension argument (see (2.14) and (2.15) in section 2) shows that the only cases to consider are the following: (1) n=4 and M minimal, (2) n=4 and M non minimal, (3) n=5 and M non minimal.

The main result is

MAIN THEOREM. Let $f: M \to \mathbb{R}^n(c)$ be an isometric immersion of a compact connected surface in a n-dimensional space form of constant curvature c (with n = 4, 5). If

- (a) the second fundamental form of M is conformal (and not zero) and
- (b) the mean curvature vector field H is parallel or, if H = 0, the length of h is constant, then:
- (1) if n = 4 and M is minimal, then M coincides with the Veronese surface in S^4 ,
- (2) if n = 4 and M is not minimal, then c = 0 and M coincides with the Clifford torus immersed in \mathbb{R}^4 ,
- (3) if n = 5 then f is an immersion of \mathbb{RP}^2 in S^5 , which factors throught the Veronese surface in a suitable S^4 in S^5 .

In any case M is a pseudoumbilical submanifold and it is either minimal in $\mathbb{R}^n(c)$ or minimally immersed in a small hypersphere of $\mathbb{R}^n(c)$.

The proof of the Main Theorem will be given in section 3. In particular (1) is a consequence of theorem 3.2, (2) follows from theorem 3.4 and (3) from theorem 3.6.

In section 2 some algebraic problems concerning the condition that h is conformal are examined and it will be shown that this condition is equivalent to some other notions which were introduced by SIMONS [10] and B.Y. Chen [1].

Section 3 is devoted to the study of surfaces with codimension greater than one; in particular this yields the proof of the main theorem, which gives a new characterization of the Clifford torus and the Veronese surface.

In the case of m-dimensional submanifolds (m > 2) it seems unlikely that a complete classification could be done. In a forthcoming paper some problems concerning the submanifolds with dimension greater than two with conformal second fundamental form will be analyzed.

2 - Preliminaries and conditions equivalent to h conformal

Let M be a m-dimensional manifold isometrically immersed in a n-dimensional manifold N.

In this section I will use the following sets of indices with the following ranges:

$$A, B, ... = 1, ..., n$$

 $i, j, ... = 1, ..., m$
 $\alpha, \beta, ... = m + 1, ..., n$.

Furthermore repeated indices are summed over the respective ranges. Let $(e_A) = (e_i, e_\alpha)$ be an orthonormal moving frame of N adapted to M (which is called a Darboux frame). This is equivalent to say that, restricted to M, e_i are tangent vector fields to M (in fact they are a local frame on M) and the e_α are normal vector fields to M.

If (ω^A) denotes the dual frame of (e_A) and ω_B^A are the Levi-Civita connection forms on N, then the structure equations of N are given by (compare [3])

(2.1)
$$d\omega^A = -\omega_B^A \wedge \omega^B \qquad (\omega_A^B + \omega_B^A = 0)$$

(2.2)
$$d\omega_B^A = -\omega_C^A \wedge \omega_B^C + \frac{1}{2} R_{ABCD}^N \omega^C \wedge \omega^D$$

where \mathbb{R}^N is the curvature tensor of N. If N is a space of constant curvature c then

$$R_{ABCD}^{N} = c(\delta_{AC}\delta_{BD} - \delta_{AD}\delta_{BC}).$$

If the forms ω^A are restricted to M, then (ω^i) is the orthonormal coframe of M, the Levi Civita connection of M is defined by (ω_j^i) , and

$$(2.3) \omega_i^{\alpha} = h_{ij}^{\alpha} \omega^j, h_{ij}^{\alpha} = h_{ji}^{\alpha} = (\nabla_{e_i}^N e_j, e_{\alpha}) = (h(e_i, e_j), e_{\alpha}).$$

Hence the h_{ij}^{α} are the components of the second fundamental form, which is a TM^{\perp} valued bilinear symmetric form on M. In addition, one has the following formulas

(2.4)
$$R_{ijhk}^{M} = R_{ijhk}^{N} + h_{ih}^{\alpha} h_{jk}^{\alpha} - h_{ik}^{\alpha} h_{jh}^{\alpha} \qquad \text{(Gauss equations)},$$

$$(2.5) R_{\alpha\beta ij}^{\perp} = R_{\alpha\beta ij}^{N} + h_{ki}^{\alpha} h_{ik}^{\beta} - h_{kj}^{\alpha} h_{ki}^{\beta} (Ricci equations),$$

where R^{\perp} is the curvature tensor of the Riemannian connection ∇^{\perp} in the normal bundle TM^{\perp} determined by the forms $(\omega_{\beta}^{\alpha})$. The covariant derivative of the second fundamental form is $\bar{\nabla}h$ and it has components h_{ijk}^{α} , where $h_{ijk}^{\alpha} = ((\bar{\nabla}_{e_k}h)(e_i, e_j), e_{\alpha})$ and

$$(\bar{\nabla}_{e_k}h)(e_i,e_j) = \nabla^{\perp}_{e_k}(h(e_i,e_j)) - h(\nabla^{M}_{e_k}e_i,e_j)h(e_i,\nabla^{M}_{e_k}e_j).$$

In terms of the forms ω_R^A

$$(2.6) h_{ijk}^{\alpha}\omega^{k} = dh_{ij}^{\alpha} - h_{kj}^{\alpha}\omega_{i}^{k} - h_{ik}^{\alpha}\omega_{j}^{k} + h_{ij}^{\beta}\omega_{\beta}^{\alpha} (h_{ijk}^{\alpha} = h_{jik}^{\alpha}).$$

Exterior differentiation of (2.3) yields

(2.7)
$$h_{ijk}^{\alpha} = h_{ikj}^{\alpha} + R_{\alpha ikj}^{N} \quad \text{(Codazzi equations)}.$$

The mean curvature vector field H of the immersion of M in N is defined by

$$(2.8) H = \frac{1}{m} h_{ii}^{\alpha} e_{\alpha}.$$

M is minimal in N if H=0; M has parallel mean curvature if H is parallel with respect to the normal connection i.e. $\nabla^{\perp}H=0$ or

$$h_{iik}^{\alpha}=0.$$

The (n-m) symmetric matrices of order m which are determined by h, are

$$(2.10) H_{\alpha} = (h_{ij}^{\alpha}).$$

The norm (or length) of h is given by

(2.11)
$$||h||^2 = \sum_{i,j,\alpha} (h_{ij}^{\alpha})^2 = \sum_{\alpha} ||H_{\alpha}||^2,$$

where the scalar product and the norm of matrices are defined in the usual way: if $A = (a_{ij})$ and $B = (b_{ij})$ then

$$(A,B) = \operatorname{trace}({}^{t}AB) = \sum a_{ij}b_{ij}$$
.

DEFINITION 2.1. The second fundamental form of the immersion of M in N is conformal if there exists a function λ on M such that

$$(2.12) (H_{\alpha}, H_{\beta}) = \lambda^2 \delta_{\alpha\beta}.$$

In other words the matrices (H_{α}) are orthogonal and they have the same length.

(2.12) implies, in particular, that, if h is conformal, then

(2.13)
$$||h||^2 = (n-m)\lambda^2.$$

I will suppose $n-m\geq 2$, as it is trivially true that a hypersurface has conformal second fundamental form. It also will be assumed that λ is not identically zero, or, in other terms, that M is not totally geodesic in N. As the dimension of the vector space of the symmetric matrices of order m is $\frac{m(m+1)}{2}$, one can notice that the second fundamental form is conformal (and not zero) only if the H_{α} are linear independent, hence

$$(2.14) n-m \leq \frac{m(m+1)}{2}.$$

Furthermore, if M is minimal in N, the matrices (H_{α}) belong to the hyperplane of the traceless symmetric matrices. Hence h is conformal only if

$$(2.15) n-m \leq \frac{m(m+1)}{2}-1.$$

In the last part of this chapter it will be shown that 'h conformal' is equivalent to some other conditions.

Let S(M) be the fibre bundle of symmetric endomorphisms on TM and let $A \in \text{hom}(TM^{\perp}, S(M))$ be the operator associated to h, i.e.

$$(h(X,Y),w)=(A_w(X),Y).$$

For the Darboux frame (e_i, e_{α})

$$A_{e_{\alpha}}=H_{\alpha}$$
.

J. SIMONS, [10], introduced the operator $\tilde{A} \in \text{hom}(TM^{\perp}, TM^{\perp})$, defined by

$$\tilde{A} = {}^t A A$$

where ${}^{t}A$ is the adjoint operator of A (i.e. $({}^{t}A(s), w) = (A(w), s)$).

It can be easily verified that

$$(\tilde{A}(e_{\alpha}),e_{\beta})=(A_{e_{\alpha}},A_{e_{\beta}})=h_{ij}^{\alpha}h_{ij}^{\beta}$$

Hence h is conformal if and only if

$$\tilde{A} = \lambda^2 I,$$

where I is the identity.

On the other hand, B.Y. CHEN, [1], introduced, for any normal vector field ξ , the allied vector field $a(\xi)$ defined as follows: if (e_{α}) is an orthonormal moving frame such that $e_{m+1} = \frac{\xi}{\|\xi\|}$ then one defines, if $\xi \neq 0$

$$(2.17) \quad a(\xi) = \frac{\|\xi\|}{m} \sum_{\beta=m+2}^{n} \operatorname{trace}(H_{m+1}H_{\beta})e_{\beta} = \frac{\|\xi\|}{m} \sum_{\beta=m+2}^{n} (H_{m+1}, H_{\beta})e_{\beta},$$

otherwise, if $\xi = 0$, $a(\xi) = 0$.

From (2.17) follows that h is conformal if and only if, for any $\xi \in TM^{\perp}$, $a(\xi) = 0$. Hence

THEOREM 2.1. If M is a submanifold of a Riemannian manifold N then the following are equivalent:

- (1) the second fundamental form is conformal,
- (2) the Simons operator $\tilde{A} \in \text{hom}(TM^{\perp}, TM^{\perp})$ is proportional to the identity,
- (3) for any normal vector field, the allied vector field vanishes.

REMARK. Any submanifold for which a(H)=0 is called a A-submanifold or Chen-submanifold ([1], [4]). The class of Chen submanifolds includes the hypersurfaces, the minimal submanifolds and, more generally, the pseudoumbilical submanifolds -that is the submanifolds such that for any $X,Y\in TM$

$$(h(X,Y),H) = (X,Y)||H||^2,$$

or, in other words, such that A_H is proportional to the identity (i.e. the section H is umbilical). In fact, if M is pseudoumbilical, H_{n+1} is a multiple of the identity matrix and all H_{β} for $\beta \geq m+2$ are traceless, hence a(H) vanishes.

3 - Surfaces with conformal second fundamental form

If $\operatorname{codim}(M) > 1$, from all what was remarked in section 2 it follows that the study of the condition that the second fundamental form of a surface is conformal can be done considering separately the following situations:

- (1) M is a minimal surface in a 4-dimensional manifold
- (2) M is a non-minimal surface in a 4-dimensional manifold
- (3) M is a non-minimal surface in a 5-dimensional manifold.

In this section, examples of any of these three cases will be examined. It will be given particular attention to the case in which N is a space of constant curvature and M has parallel mean curvature.

3.1 - Minimal surfaces in a 4-dimensional manifold

Whatever is the Darboux frame (e_A) , the matrices H_3 and H_4 (defined by (2.10) have zero trace. With a suitable choice of the frame (e_1, e_2) of M, it can be assumed that one of these matrices, say H_3 , is diagonal. The condition that h is conformal implies that, if the orientation of e_4 is appropriately chosen, the matrices H_3 and H_4 are

$$(3.1) H_3 = \begin{pmatrix} \mu & 0 \\ 0 & -\mu \end{pmatrix}, H_4 = \begin{pmatrix} 0 & \mu \\ \mu & 0 \end{pmatrix},$$

where μ is a function on M, not identically zero, unless M is totally geodesic.

For any $X = X_1e_1 + X_2e_2$ tangent to M

$$h(X,X) = (\mu X_1^2 - \mu X_2^2)e_3 + 2\mu X_1 X_2 e_4$$

hence

$$||h(X,X)|| = |\mu||X||^2$$

which means that M is a isotropic minimal submanifold of N as introduced by O' Neill [8]. It can be verified easily that the converse is also true, hence

THEOREM 3.1. A surface minimally immersed in a 4-dimensional manifold has conformal second fundamental form if and only if it is isotropic.

If N is a space of constant curvature c, then, from (2.4), (2.5) and (3.1) follows that the Gaussian curvature K and the normal curvature K^{\perp} of N are given by

(3.3)
$$K = R_{1212}^M = c - 2\mu^2, \qquad K^{\perp} = R_{3412}^{\perp} = 2\mu^2,$$

and

(3.4)
$$d\omega_2^1 = K\omega^1 \wedge \omega^2, \qquad d\omega_4^3 = K^\perp \omega^1 \wedge \omega^2.$$

A significative example of minimal surface in a space of constant curvature with conformal second fundamental form is the Veronese surface in S^4 . If $S^2(R)$ is the sphere in \mathbb{R}^3 with centre in the origin and radius R, then the mapping (3.5)

$$f: \mathbb{R}^3 \to \mathbb{R}^5: (x, y, z) \mapsto \frac{1}{R}(xy, xz, yz, \frac{1}{2}(x^2 - y^2), \frac{1}{2\sqrt{3}}(x^2 + y^2 - 2z^2))$$

induces an isometric immersion of $S^2(R)$ in $S^4(\frac{R}{\sqrt{3}})$. As antipodal points are mapped by f to the same point of $S^4(\frac{R}{\sqrt{3}})$, one obtains an isometric

immersion of the real projective plane \mathbb{RP}^2 in $S^4(\frac{R}{\sqrt{3}})$, which is called the Veronese surface.

An easy computation in local coordinates shows that one can choose a Darboux frame (e_1, e_2, e_3, e_4) so that

$$(3.6) H_3 = \begin{pmatrix} \frac{1}{R} & 0 \\ 0 & -\frac{1}{R} \end{pmatrix}, H_4 = \begin{pmatrix} 0 & \frac{1}{R} \\ \frac{1}{R} & 0 \end{pmatrix},$$

and setting $\mu = \frac{1}{R}$ one can see that (3.6) coincides with (3.1). Conversely, if one supposes that in (3.1) μ is constant (i.e that the second fundamental form has constant length) and if one takes exterior differentiation of the formulas (which are just (3.1) restated)

(3.1')
$$\omega_1^3 = \mu \omega^1$$
, $\omega_2^3 = -\mu \omega^2$, $\omega_1^4 = \mu \omega^2$, $\omega_2^4 = \mu \omega^1$,

then it follows that

$$\omega_4^3 = 2\omega_2^1,$$

whence, using (3.3) and (3.4), one obtains

$$K^{\perp} = 2\mu^2 = 2K = 2c - 4\mu^2,$$

hence

(3.8)
$$c = 3\mu^2, \quad K = \mu^2.$$

In particular (3.8) implies that M is a space of constant curvature. Hence the same argument as in the proof of theorem 3, page 72 of [3] shows that M coincides locally (globally if M is compact) with the Veronese surface. (Formulas (4.12) and (4.13) of [3] are the same as (3.7) and (3.8)).

This proves the following

THEOREM 3.2. Let N be a space form of dimension 4 and let M be a connected minimal surface of N with second fundamental form conformal and of constant length; then

- (1) the curvature of N is positive
- (2) M coincides locally with the Veronese surface in S⁴; if M is compact it coincides with the Veronese surface.

One can achieve the same result starting from different assumptions. As a matter of fact it will be proved the following

THEOREM 3.3. Let N be a space form of dimension 4 and let M be a compact and connected minimal surface of M with conformal second fundamental form. If K is the Gaussian curvature of M, K^{\perp} is the normal curvature of M and if

$$(3.9) 2K \ge K^{\perp} or 2K \le K^{\perp}$$

everywhere on M, then $2K = K^{\perp}$, N has positive sectional curvature and M coincides with the Veronese surface.

PROOF. It will be proved that (compare also [5])

$$\Delta \log \mu = 2K - K^{\perp},$$

where Δ is the Laplace-Beltrami operator on M, that acts on scalars according to the following formula

(3.11)
$$\Delta f = \nabla_{e_i e_i}^2 f = e_i e_i f - \nabla_{e_i} e_i f.$$

Taking exterior differentiation of (3.1) and using the equations of Codazzi it follows

$$e_1\mu = -\mu(\omega_4^3 - 2\omega_2^1)(e_2), \qquad e_2\mu = \mu(\omega_4^3 - 2\omega_2^1)(e_1).$$

An easy computation shows that

$$\Delta \log \mu = 2d\omega_2^1(e_1, e_2) - d\omega_4^3(e_1, e_2) = 2K - K^{\perp}.$$

As M is compact

$$0 = \int_{M} \Delta log\mu dM = \int_{M} (2K - K^{\perp}) dM$$

applying (3.9), $\Delta log \mu = 0$: hence μ is constant.

REMARK. Theorems 3.2 and 3.3 show a remarkable feature of the Veronese surface. On the other hand, it is possible to find examples of surfaces that are minimally immersed in a space form of dimension 4 with second fundamental form conformal but not of constant length.

For instance, if one sets z = x + iy, the surface immersed in \mathbb{R}^4 , which is the image of $\mathbb{C} - \{0\}$ by the map

$$(\text{Re}(z^3), \text{Im}(z^3), \text{Re}(z^2), \text{Im}(z^2))$$

or $(x^3 - 3xy^2, 3x^2y - y^3, x^2 - y^2, 2xy),$

has conformal second fundamental form.

To see this, set

$$P_x = (3x^2 - 3y^2, 6xy, 2x, 2y),$$
 $P_y = (-6xy, 3x^2 - 3y^2, -2y, 2x),$

so that $e_1 = \frac{P_x}{\|P_x\|}$ and $e_2 = \frac{P_y}{\|P_y\|}$ is an orthonormal frame. If

$$e_3 = \frac{1}{\|P_x\|}(2x, 2y, -3(x^2+y^2), 0),$$

$$e_4 = \frac{1}{\|P_x\|}(-2y, 2x, 0, -3(x^2 + y^2)),$$

one can readily compute the second fundamental form, finding

$$\begin{split} h_{11}^3 &= -h_{22}^3 = h_{12}^4 = \frac{1}{\|P_x\|^5} (x^2 + y^2)^2 (24 + 54(x^2 + y^2)), \\ h_{12}^3 &= h_{11}^4 = h_{22}^4 = 0. \end{split}$$

This example can be found in [7], page 41.

3.2 - Non minimal surfaces in a 4-dimensional manifold

It can be easily verified that one can choose the Darboux frame so that e_4 is parallel to the mean curvature vector H of M in N and the matrix H_4 is diagonal: that is

$$H_4 = \begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix}, \qquad \alpha + \beta \neq 0.$$

The trace of H_3 is zero, so H_3 is of the kind

$$H_3 = \begin{pmatrix} \gamma & \delta \\ \delta & -\gamma \end{pmatrix}$$
.

The orthogonality of H_3 and H_4 implies

$$(\alpha - \beta)\gamma = 0,$$
 $\alpha^2 + \beta^2 = 2\gamma^2 + 2\delta^2.$

It follows that two case are possible

(1) if $\alpha \neq \beta$, i.e. M is not pseudoumbilical, then $\gamma = 0$, so

(3.12)
$$H_3 = \begin{pmatrix} 0 & \delta \\ \delta & 0 \end{pmatrix}, \qquad H_4 = \begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix},$$

(2) if M is pseudoumbilical, $\alpha = \beta$ and one can choose (e_1, e_2) so that H_3 and H_4 are

(3.13)
$$H_{3} = \begin{pmatrix} \alpha & 0 \\ 0 & -\alpha \end{pmatrix} \quad \text{or} \quad H_{3} = \begin{pmatrix} 0 & \alpha \\ \alpha & 0 \end{pmatrix},$$
$$H_{4} = \begin{pmatrix} \alpha & 0 \\ 0 & \alpha \end{pmatrix}.$$

It can be remarked that the two different expressions of of H_3 in (3.13) are reducible one to the other by means of a reflection with respect to bisector of the angle (e_1, e_2) . Hence no geometric distinction between this last two cases holds. In both cases (1) and (2) H_3 and H_4 can be expressed as follows:

(3.14)

$$H_3 = \begin{pmatrix} 0 & \delta \\ \delta & 0 \end{pmatrix}, \qquad H_4 = \begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix}, \qquad \alpha + \beta \neq 0, \qquad \alpha^2 + \beta^2 = 2\delta^2.$$

cases (1) or (2) occurring according to $\alpha \neq \beta$ or $\alpha = \beta$ respectively.

An example of a non pseudoumbilical surface satisfing (3.12) is the following surface of \mathbb{R}^4 :

$$(3.15) \qquad (f(u)\cos v, f(u)\sin v, \cos(\sqrt{2}v), \sin(\sqrt{2}v)),$$

where f is any function with $f' \neq 0$.

Such a surface is a particular case of a type of Chen-submanifolds, which can be found in [4].

An important example of pseudoumbilical surface with conformal second fundamental form is the Clifford torus immersed in \mathbb{R}^4 :

(3.16)
$$P: S^{1}(R) \times S^{1}(R) \to \mathbb{R}^{4}$$

$$(u, v) \mapsto P(u, v) = (R \cos u, R \sin u, R \cos v, R \sin v).$$

which is, as well known, a flat minimal surface in $S^3(\sqrt{2}R)$. Set

$$e_1 = P_u / ||P_u|| = (-\sin u, \cos u, 0, 0),$$

 $e_2 = P_v / ||P_v|| = (0, 0, -\sin v, \cos v).$

Then $H = -\frac{1}{R}(\cos u, \sin u, \cos v, \sin v)$.

Hence H is orthogonal to $S^3(\sqrt{2}R)$, which means that the torus is minimal in the sphere. If $e_4 = \frac{H}{\|H\|}$, $e_3 = \frac{1}{\sqrt{2}}(-\cos u, -\sin u, \cos v, \sin v)$ it can be easily seen that

$$H_3 = rac{1}{\sqrt{2}R} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \qquad H_4 = rac{1}{\sqrt{2}R} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

The importance of the immersion of the Clifford torus in \mathbb{R}^4 is clarified by the following

THEOREM 3.4. Let N be a space form of dimension 4 with curvature c and let M be a compact and connected surface with conformal second fundamental form and with parallel and non vanishing mean curvature vector field. Then:

- (1) N is flat (i.e. $N = \mathbb{R}^4$)
- (2) M coincides with the Clifford torus.

PROOF. By (3.14), (2.4) and (2.5) yield

(3.17)
$$K = R_{1212}^{M} = c + \alpha \beta - \delta^{2},$$

(3.18)
$$K^{\perp} = R_{3412}^{\perp} = (\beta - \alpha)\delta,$$

from which follows that the normal curvature of M vanishes if and only if M is pseudoumbilical.

(2.6) implies, using the parallelism of the mean curvature vector and (3.16),

$$(\alpha + \beta)\omega_A^3 = 0,$$
 $d(\alpha + \beta) = 0.$

Hence $(\alpha + \beta)$ is constant, $\omega_4^3 = 0$ and therefore $K^{\perp} = 0$, i.e. $\alpha = \beta$.

Thus, M is a pseudoumbilical submanifold of N and (by (3.17) and the conformity of h) its Gaussian curvature K is given by:

$$K=c$$
.

On the other hand the section e_3 is parallel, isoperimetric and umbilical hence ([1] prop. 5.1 page 124)

$$K=0$$
.

whence, as N is simply connected, $N = \mathbb{R}^4$. Let \tilde{X} be the position vector field of \mathbb{R}^4 , and let Y be any tangent vector to M; as $H = \alpha e_4$ and α is constant

$$\nabla_Y^{\mathbf{R}^4}(\tilde{X} + \frac{1}{\alpha}e_4) = Y - \frac{1}{\alpha}A_{e_4}(Y) = Y - Y = 0$$

hence $(\bar{X} + \frac{1}{\alpha}e_4)$ is a constant vector a: therefore M is cointained in the 3-sphere centered at a and with radius $\frac{1}{\alpha} = \frac{1}{\|H\|}$, H is orthogonal to the sphere, which implies that M is minimal in the sphere. Thus, if M is compact, it follows by the same argument as in the proof of Theorem 2, page 70 of [3] (in the case of a surface) that M coincides with the Clifford torus in \mathbb{R}^4 .

REMARK. One can notice that by (3.18) (if N has constant curvature and M is a non minimal surface with conformal second fundamental form) the vanishing of the normal curvature of M is equivalent to the pseudoumbilicity of M. On the other hand ([1] prop. 2.4 page 179), for a pseudoumbilical submanifolds of codimension 2 in a space form ||H|| is constant if and only H is parallel. The following example shows that there exist pseudoumbilical surfaces of codimension 2 with conformal second fundamental form and H non parallel. An easy computation shows that the surface in \mathbb{R}^4

$$(3.19) (u, v) \mapsto e^{u}(\cos u \cos v, \cos u \sin v, \sin u \cos v, \sin u \sin v)$$

has mean curvature vector parallel to

$$e_4 = -\frac{1}{\sqrt{2}}(\cos v(\sin u + \cos u), \sin v(\sin u + \cos u),$$
$$\cos v(\sin u - \cos u), \sin v(\sin u - \cos u)),$$

and $||H|| = e^{-u}/\sqrt{2}$.

Hence, if $e_3 = (\sin u \sin v, -\sin u \cos v, -\cos u \sin v, \cos u \cos v)$,

$$H_3 = \frac{e^{-u}}{\sqrt{2}} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \qquad H_4 = \frac{e^{-u}}{\sqrt{2}} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

3.3 - Surfaces of a 5-dimensional manifold

We choose the Darboux frame $(e_1, e_2, e_3, e_4, e_5)$, so that e_5 is parallel to H (which cannot be zero, as noticed previously), (e_1, e_2) is an orthonormal frame diagonalizing H_5 . Thus

$$H_3 = \begin{pmatrix} \gamma & \delta \\ \delta & -\gamma \end{pmatrix}, \qquad H_4 = \begin{pmatrix} \lambda & \mu \\ \mu & -\lambda \end{pmatrix}, \qquad H_5 = \begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix}.$$

The orthogonality of this matrices yields

$$(\alpha - \beta)\gamma = 0,$$
 $(\alpha - \beta)\lambda = 0.$

 $\gamma = \lambda = 0$ being impossible (unless H_3 , H_4 and H_5 are not independent), $\alpha = \beta$, i.e. the section H is umbilical. Hence

THEOREM 3.5. A surface of a 5-dimensional manifold with conformal second fundamental form is pseudoumbilical.

As this property does not depend on the choice of (e_1, e_2) , one can suppose the orthonormal frame (e_1, e_2) such that H_3 is diagonal. Because of the orthogonality of H_3 and H_4 and the equality of the norms of H_3 , H_4 and H_5 , one can assume that the second fundamental form is represented by

$$(3.20) \ \ H_3 = \begin{pmatrix} \alpha & 0 \\ 0 & -\alpha \end{pmatrix}, \qquad H_4 = \begin{pmatrix} 0 & \alpha \\ \alpha & 0 \end{pmatrix}, \qquad H_5 = \begin{pmatrix} \alpha & 0 \\ 0 & \alpha \end{pmatrix}.$$

Let now N be a space of constant curvature. (3.20) and (2.5) yield

$$R_{3412}^{\perp} = 2\alpha^2$$
.

Hence the normal curvature is not zero. If the mean curvature vector field is parallel, then M is minimal in a small sphere $S^4(r)$ of N (see Proposition 4.2 of [2]), and the section e_5 , parallel to H, is normal to $S^4(r)$ on M, whereas e_3 and e_4 are tangent to the 4-sphere. As M has conformal second fundamental form in $S^4(r)$, Theorem 3.2 implies that M is locally immersed in $S^4(r)$ as Veronese surface. By (3.20) and (2.4) the Gaussian curvature K of M as submanifold of N is

$$K = c - \alpha^2$$
.

On the other hand, as H_3 and H_4 represent the second fundamental form of the immersion of M in $S^4(r)$, if M is considered as submanifold of $S^4(r)$, by (3.8):

$$K = \frac{1}{r^2} - 2\alpha^2$$
, $K = \alpha^2$, $\frac{1}{r^2} = 3\alpha^2$.

Hence, set $\alpha = 1/R$, it follows that $r = R/\sqrt{3}$, $c = 2/R^2$. This proves the following

THEOREM 3.6. Let N be a space form of dimension 5 and let M be a compact surface with conformal second fundamental form and with parallel mean curvature vector field. Then:

- (1) N is 5-sphere
- (2) M is a sphere $S^2(R)$ immersed in $S^4(\frac{R}{\sqrt{3}})$ as Veronese surface and $S^4(\frac{R}{\sqrt{3}})$ is immersed in $S^5(\frac{R}{\sqrt{2}})$ as a totally umbilical submanifold, i.e. $S^4(\frac{R}{\sqrt{3}})$ is a section of $S^5(\frac{R}{\sqrt{2}})$ by a hyperplane at a distance $\frac{R}{\sqrt{6}}$ from the centre of $S^5(\frac{R}{\sqrt{2}})$.

REMARK 1. It is trivial that the parallelism of H implies that $\alpha = \|H\|$ is constant and therefore that the length of h is constant. Conversely, if N has constant sectional curvature and if M has conformal second fundamental form, then $\|H\| = \text{constant}$ implies that H is parallel. This result can be proven by means of a straightforward computation,

differentiating the forms ω_i^{α} ($i=1,2;\alpha=3,4,5$) whose coefficients are expressed by (3.20) with $\alpha=\|H\|=$ constant (hence the result is a consequence of the Codazzi conditions). Therefore the Veronese surface immersed in a 5-sphere as in Theorem 5 is the only example of surface immersed in 5-dimensional space of constant curvature with second fundamental form conformal and of constant length.

REMARK 2. A more general version of Theorem 5 can be stated: Let $q: M \to \mathbb{R}^5(c)$ be an isometric immersion of a surface with conformal second fundamental form. If N is any Riemannian 4-dimensional manifold and q factors throught a minimal immersion $f: M \to N$ and an immersion $g: N \to \mathbb{R}^5(c)$ then the length of the second fundamental form of q, h_q , is constant and q is locally the immersion of the 2-sphere in the 5-sphere of Theorem 5.

To prove this, one notices that the mean curvature vector H of q is orthogonal to N. Hence, using the well known identity $h_q = h_f + f^*h_g$, it can be recognized that one can choose a Darboux frame $(e_1, e_2, e_3, e_4, e_5)$ adapted to the two immersions f and g such that the matrices H_3 and H_4 (which represent h_f) and H_5 (which is the matrix of f^*h_g) are in the form (3.20). In particular, for any X and Y tangent to M, $h_g(X,Y) = (X,Y)H$, and the equations of Codazzi for the immersion g yield $||H|| = \alpha = \text{constant}$.

REMARK 3. If one considers the immersion of $S^2(R)$ in \mathbb{R}^5 defined by (3.5), it can be easily verified that, chosen e_5 parallel to H, which is orthogonal to $S^4(\frac{R}{\sqrt{3}})$ one obtains that H_5 is given by

$$H_5 = \frac{\sqrt{3}}{R} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix},$$

and that H_3 and H_4 are given by (3.6). Hence the H_i are orthogonal but with different norms. By modifing the canonical metric of \mathbb{R}^5 properly, one can obtain an immersion with conformal second fundamental form. If ρ denotes the radial coordinate and (θ^i) (i=1,..,4) is an orthonormal coframe of $S^4(1)$, then the canonical metric of \mathbb{R}^5 is given by

$$ds^2 = d\rho^2 + \rho^2(\sum (\theta^i)^2).$$

If one considers the metric of IR⁵

$$ds_1^2 = 3d\rho^2 + \rho^2(\sum (\theta^i)^2),$$

then (3.5) define an immersion in (\mathbb{R}^5, ds_1^2) with conformal second fundamental form. It must be remarked, however, that (\mathbb{R}^5, ds_1^2) is not a space of constant curvature.

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